TOPIC : CENTRE OF MASS EXERCISE # 1

SECTION (A)

- 1. Centre of mass is a point which can lie within or outside the body.
- 2. Self explaintory
- 4. Centre of mass is nearer to heavier mass

5. we have m1 r1 = m2 r2 \Rightarrow mr = 2m (3a - r) \Rightarrow r = 2a

6. r = 1.27 Å

$$\begin{split} r_{cm} & \frac{m_1 r_1 + m_2 r_2}{m_1 + m_2} \\ r_{cm} & \frac{0 + 35.5 \times 1.27}{35.5 + 10} = \frac{35.5 \times 1.27}{36.5} \\ = 1.24 \text{ Å} \end{split}$$

$$h-y$$

 dy
 b

13.

Let mass of strip is dm

$$dm = \frac{2m}{bh} \times x \, dy \qquad \Rightarrow \qquad \frac{h}{b} = \frac{h-y}{x} \qquad \Rightarrow \qquad x = b - \frac{h}{h} y$$

$$y_{cm} = \frac{\int_{0}^{h} y \, dm}{\int_{0}^{h} dm} = \frac{\int_{0}^{h} y \left(\frac{2m}{bh}\right) \left(b - \frac{by}{h}\right) dy}{\int_{0}^{h} \frac{2m}{bh} \left(b - \frac{by}{h}\right) dy} = \frac{\left(\frac{by^{2}}{2} - \frac{by^{3}}{3h}\right)_{0}^{h}}{\left(by - \frac{by^{2}}{2h}\right)_{0}^{h}} = \frac{h}{3}$$

$$y_{cm} = \frac{h}{3} \qquad y_{cm} = \frac{h}{3}$$

$$x_{cm} = \frac{3 \times \frac{1}{2} + 2 \times 1}{6} = \frac{3.5}{6} = \frac{35}{60} = \frac{7}{12} \qquad \Rightarrow \qquad Y_{cm} = \frac{\sqrt{\frac{3}{2} \times 3}}{6} = \frac{\sqrt{3}}{4}$$

$$x_{cm} = \frac{\int dm x}{\int dm} = \frac{\int (\lambda dx)x}{\int \lambda dx} = \frac{\int_{0}^{h} \lambda_{0} x^{2} dx}{\int_{0}^{h} \lambda_{0} x dx} = \frac{2L}{3}$$

$$19. \qquad A_{1} = \pi R_{2} \qquad A_{2} = \frac{\pi R^{2}}{16} \qquad \Rightarrow \qquad x_{1} = 0 \qquad x_{2} = \frac{3R}{4}$$

$$\frac{0 - \frac{\pi R^{2}}{16} \times \frac{3R}{4}}{\pi R^{2} - \frac{\pi R^{2}}{16}} = -\frac{R}{20}$$

$$x_{cen} = 20. \qquad \text{Let } m_{1} = m, m_{2} = 2m, m_{3} = 3m, m_{4} = 4m$$

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$$\vec{r}_{1} = \frac{m_{1}\vec{r}_{1} + m_{2} + m_{3} + m_{4}}{m_{1} + m_{2} + m_{3} + m_{4}} = 0.95ai + \frac{\sqrt{3}}{4}aj$$

$$\vec{r}_{2} = \frac{m_{1}\vec{r}_{1} + m_{2}r_{2}}{m_{1} + m_{2} + m_{3} + m_{4}} \begin{bmatrix} 0.95ai + \frac{\sqrt{3}}{4}aj \\ 0.95ai + \frac{\sqrt{3}}{4}aj \end{bmatrix}$$

21. According to figure let A is the origin and co-ordinates of centre of mass be (x, y) then,



22. Linear density of the rod varies with distance $\frac{dm}{dx} = \lambda$ (Given) $\therefore dm = \lambda dx$ $\int dm x x$

$$x_{cm} = \frac{\int dm x x}{\int dm}$$

Position of centre of mass

$$= \frac{\int_{0}^{3} (\lambda \, dx) x x}{\int_{0}^{3} (\lambda \, dx) x x} = \frac{\int_{0}^{3} (2+x) x \, x dx}{\int_{0}^{3} (2+x) dx} = \frac{\left[x^{2} + \frac{x^{3}}{3} \right]_{0}^{3}}{\left[2x + \frac{x^{3}}{2} \right]_{0}^{3}} = \frac{9+9}{6+\frac{9}{2}} = \frac{36}{21} = \frac{12}{7} \text{ m}$$



23.

26.

Coordinate of centre of mass of large disc at its centre (0, 0) coordinate of centre of mass of small disc (7, 0)

$$X_{CM} = \frac{m_{1}X_{1} + m_{2}X_{2}}{m_{1} + m_{2}}$$

$$X_{CM} = \frac{m_{1}X_{1} + m_{2}X_{2}}{m_{1} + m_{2}}$$

$$M_{1} = \frac{m_{2}}{m_{2}} = \frac{m_{1}X_{1} + m_{2}X_{2}}{m_{1} + m_{2}}$$

$$M_{1} = (-\sigma) \pi (21 \text{ cm})_{2}$$

$$X_{CM} = \frac{0 \times m_{2} + (-\sigma)\pi(21 \text{ cm})^{2}}{6\pi(28 \text{ cm})^{2} + (-\sigma)\pi(21 \text{ cm})^{2}} = -9 \text{ cm}$$

$$Y_{CM} = 0$$
24.
$$X_{CM} = \frac{0 + m \times a + m \times 0}{3m} = \frac{a}{3} \implies Y_{CM} = \frac{0 + M \times 0 + M(a)}{3M} = \frac{a}{3}$$
25.
$$(i) X_{CM} = \frac{0 \times m + m \times a + m \times \frac{a}{2}}{m_{1} + m_{2} + m_{3}} = \frac{a}{2}, \implies Y_{CM} = \frac{0 \times m + 0 \times m + m \times \frac{a\sqrt{3}}{2}}{m_{1} + m_{1} + m_{2}} = \frac{a\sqrt{3}}{6},$$
26.
$$X_{CM} = \frac{m_{1}X_{1} + m_{2}X_{2} + m_{3}X_{3}}{m_{1} + m_{2}Y_{2} + m_{3}Y_{3}} = \frac{(1)(0) + (1)(1) + 2(1/2)}{1 + 1 + 2} = 0.50 \text{ m and}$$

$$Y_{CM} = \frac{m_{1}Y_{1} + m_{2}Y_{2} + m_{3}Y_{3}}{m_{1} + m_{2} + m_{3}} = \frac{(1)(0) + (1)(0) + 2(\sqrt{3}/2)}{1 + 1 + 2} = 0.43 \text{ m}$$
The centre of mass is at (0.50 m, 0.43 m)
27. The position vector of centre of mass
$$\Rightarrow m_{1}\overline{f_{1}} + m_{1}\overline{f_{2}} = 1(\overline{f_{1}} + 2\overline{f_{1}} + \overline{k}) + 3(-3\overline{f_{2}} - 2\overline{f_{1}} + \overline{k}) = 1$$

$$(-\sigma) \times M_{1} + m_{2} + m_{3} = \frac{1}{2} + (\overline{f_{1}} + 2\overline{f_{1}} + \overline{k}) = 1$$

$$\vec{r} = \frac{\vec{m_1 r_1} + \vec{m_1 r_2}}{\vec{m_1} + \vec{m_2}} = \frac{1(\hat{i} + 2\hat{j} + \hat{k}) + 3(-3\hat{i} - 2\hat{j} + \hat{k})}{1 + 3} = \frac{1}{4}(-8\hat{i} - 4\hat{j} + 4\hat{k}) = -2\hat{i} - \hat{j} + \hat{k}$$

The centre of mass changes its position only under the translatory motion. There is no effect of rotatory motion on centre of mass of the body.

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If mass of bigger disc is M then mass of removed disc is $\overline{4}$ 28.

$$r_{CM} = \frac{\frac{M \times 0 - \frac{M}{4}R}{M - \frac{M}{4}}}{\frac{M}{4}} = \frac{R}{3} = \alpha R \implies \alpha = \frac{1}{3}$$

29. Let the two half rings be placed in left and right of y-axis with centre as shown in figure.



Then the coordinate of centre of mass of left and right half rings are



m

: x-coordinates of centre of mass of comple ring is



30.

5.

Coordinate of large disc (0, 0)Coordinate of small disc (R/2, 0)

$$X_{CM} = \frac{0 + (-\sigma)\frac{\pi R^2}{4} \cdot \frac{R}{2}}{\sigma \pi R^2 - \sigma \frac{\pi R^2}{4}} = \frac{R}{6}$$
, $Y_{CM} = 0$
 $\frac{h}{2} = \frac{40}{40}$

31. Centre of mass are
$$r_{cm} = 4 = 4 = 10$$
 cm

SECTION (B)

- 2. In abscence of external force both move away from each other to keep the centre of mass at rest.
- **3.** Internal forces canot change velocity but can do work.
- 4. If initial velocity of system is not zero then centre of mass moves with constant velocity.

 $a_{cm} = \frac{\frac{m_1 g + m_2 g}{m_1 + m_2}}{1} = g$

6.
$$v_{cm} = \frac{\frac{1 \times 2 + \frac{1}{2} \times 6}{1 + 1/2}}{\frac{10}{3}} = \frac{10}{3} \text{ m/sec}$$

7. vector sum of internal forces on system is zero.

8.
$$V_{cm} = \frac{M_1 V_1 + M_2 V_2}{M_1 + M_2} = \frac{200 \times 10\hat{i} + 500(3\hat{i} + 5\hat{j})}{700} = 5\hat{i} + \frac{25}{7}\hat{j}$$

9. $V_{CM} = 0$, because internal force cannot change the velocity of centre of mass

$$\frac{m}{4}$$
 $\frac{3m}{4}$ $\frac{4u}{3}$

14. by conservation of linear momentum $P_i = P_f \Rightarrow mu = \frac{4}{4} \times 0 + \frac{4}{4} \times V \Rightarrow v = \frac{3}{4}$

17.
$$a = \frac{(nm-m)}{nm+m}g = \frac{(n-1)}{(n+1)}g$$

$$a_{1} = a_{2} = a$$

$$a_{1} = \frac{nm}{nm}$$

$$a_{1} = \frac{nma_{1} - ma_{2}}{(nm+m)} = \frac{(n-1)}{(n+1)} \times a$$

$$a_{2} = \frac{nma_{1} - ma_{2}}{(n+1)^{2}}g$$

- 18. Equation of motion $Mg + R = Ma_{cm}$ $\vec{a}_{cm} = \frac{Mg + R}{M}$
- **19.** Let the tube displaced by x towards left, then block will be displaced by (R x) towards right ;

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 $x = \frac{R}{2}$

mx = m (R - x)

20. Net external force on box plus ball system is zero.

21.
$$m(L-x) + \frac{m}{3}(-x) = 0 \implies mL = \frac{4}{3}mx$$

22. $a_{cm} = \frac{30}{(10+20)} = 1 ms_2 \implies S = 0 (2) + \frac{1}{2} (1) (2)_2 = 2 m$
23. Acceleration of the system
 $g_{\frac{1}{2}} = \frac{1}{2} = \frac$

$$\Rightarrow \qquad \overrightarrow{a_{CM}} = \frac{1}{2}\hat{i} + \frac{1}{6}\hat{j} + \frac{1}{3}\hat{k} = \sqrt{\frac{1}{4} + \frac{1}{9} + \frac{1}{36}} = \sqrt{\frac{9+4}{36} + \frac{1}{36}} = \frac{1}{6}\sqrt{13+1} \Rightarrow \qquad \frac{\sqrt{14}}{6}ms^{-2}$$

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m₁

25.

$$\overrightarrow{V}_{CM} = \frac{m_1 \overrightarrow{V}_1 + m_2 \overrightarrow{V}_2}{m_1 + m_2} = \frac{10(2\hat{i} - 7\hat{j} + 3\hat{k}) + 2(-10\hat{i} + 35\hat{j} - 3\hat{k})}{12}$$

$$= \frac{20\hat{i} - 70\hat{j} + 30\hat{k} - 20\hat{i} + 70\hat{j} - 6\hat{k})}{12} = \frac{24\hat{k}}{12} = \frac{2\hat{k}}{12}$$

26.

The system of two given particles of masses
$$m_1$$
 and m_2 are shown in figure.
 m_1
 m_2
 m_2
 m_2
 m_2

Initially the centre of mass

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$$r_{\rm CM} = \frac{\frac{m_1 r_1 + m_2 r_2}{m_1 + m_2}}{m_1 + m_2}$$

....(i) When mass m₁ moves towards centre of mass by a distance d, then let mass m₂ moves a distance d' away from CM to keep the CM in its initial position.

$$So, r_{cm} = \frac{\frac{m_{1}(r_{1} - d) + m_{2}(r_{2} + d')}{m_{1} + m_{2}} \dots (ii)$$

Equation Eqs. (i) and (ii), we get
$$\frac{m_{1}r_{1} + m_{2}r_{2}}{m_{1} + m_{2}} = \frac{m_{1}(r_{1} - d) + m_{2}(r_{2} + d')}{m_{1} + m_{2}} \implies -m_{1}d + m_{2}d' = 0 \implies d' = \frac{m_{1}}{m_{2}}d.$$

Note: If both the masses are equal i.e., $m_1 = m_2$, then second mass will move a distance equal to the distance at which first mass is being displaced.

v

27. By the conservation of linear momentum

(m + m)v' = m. 2 v - mv
$$\Rightarrow$$
 2mv' = mv \Rightarrow v' = $\overline{2}$
28. $v_{COM} = \frac{m_1 v_1 + m_2 v_2}{m_1 + m_2}$
 $v_1 = 14 \text{ m}$
 $v_1 = 10 \text{ m}$ $w_2 = 0$
 $m_1 = 10 \text{ m}$ $m_2 = 4 \text{ m}$
 $m_1 = 10 \text{ m}$ $m_2 = 4 \text{ m}$
 $m_2 = 4 \text{ m}$
 $f(0 \times 14 + 4 \times 10)$
 $= \frac{10 \times 14 + 4 \times 10}{10 + 4} = 10 \text{ m/s.}$
29. Mass per unit length
 $\frac{M}{L} = \frac{4}{2} = 2 \text{ kg/m}$
The mass of 0.6 m of chain = 0.6 × 2 = 1.2 kg
The centre of mass of hanging part = $\frac{0.6 + 0}{2} = 0.3 \text{ m}$
Hence, work done in pulling the chain on the table
 $W = \text{mgh} = 1.2 \times 10 \times 0.3 = 1.2 \times 10 \times 0.3 = 3.6 \text{ J}$

30. Before breaking, the centre of mass of system is moving under gravity. Thus, acceleration of the centre of mass is gravitational acceleration. During breaking, internal forces come into play which are not responsible for the acceleration of the centre of mass. This indicates that, the acceleration of centre of mass remains the same (equal to gravitational

acceleration).

Thus, the centre of mass of system continues its original path.

31. for
$$\Delta x_{cm} = 0 \Rightarrow$$
 $m_1 d_1 = m_2 d_2 \therefore$ $d_2 = \frac{m_1 d_1}{m_2}$ **Ans.**

33. Initially, centre of mass of the "can + water in the can" will be at the geometrical centre of the can. As the liquid is coming out from the bottom, then centre of mass move downwards but after sometime it will move upwards and comes to its initial position. Hence, centre of mass first descends and then ascends.



34.

41.

 $\frac{M}{Mx + \frac{3}{3}} (x + L) = 0 \implies \frac{4M}{3} x = -\frac{ML}{3} \implies x = -\frac{L}{4}$ Friction force between wedge and block is internal i.e. will not ch

35. Friction force between wedge and block is internal i.e. will not change motion of COM. Friction force on the wedge by ground is external and causes COM to move towards right. Gravitational force (mg) on block brings it downward hence COM comes down.

mass of small element is $dm = \lambda dx = K(x/L)n dx$

$$x_{CM} = \frac{\int dm.x}{\int dm} = \frac{\int_{0}^{L} K.\left(\frac{x}{L}\right)^{n} dx.x}{\int_{0}^{L} K.\left(\frac{x}{L}\right)^{n} dx} = \frac{(n+1)L}{n+2}$$

So, graph shown in option (4) is correct.

SECTION (C)

1. Net external force is zero so net momentum will remain zero.

2.
$$\frac{\frac{k_2}{k_1}}{m_1} = 4$$

$$\frac{\left(\frac{v_2}{v_1}\right)^2}{m_1} = 4$$

$$\frac{\frac{v_2}{v_1}}{m_1} = 2$$

$$\frac{\left(\frac{p_2 - p_1}{p_1}\right) \times 100}{m_1} = \left(\frac{\frac{mv_2 - mv_1}{mv_1}}{m_1}\right) \times 100 = \left(\frac{v_2}{v_1} - 1\right) \times 100$$

$$= 100\%$$

- 25. Here : Mass of the body $m_1 = m$ Velocity of the first body $u_1 = 312 \text{ m/sec}$ Mass of second body at rest $m_2 = 2m$ Velocity of second body $u_2 = 0$ After combination total mass of the body M = m + 2m = 3m. Now from the law of conservation of momentum $Mv = m_1u_1 + m_2u_2$ (where M = m + 2m = 3m) $3mv = m \times 3 + 2m \times 0 \Rightarrow v = 1 \text{ km/hr}$
- For bullet, $m_1 = 50g$, $u_1 = 10 m/s$ For block, $m_2 = 950 \text{ g}$, $u_2 = 0$ 26. ⇒ From law of conservation of momentum $m_1u_1 + m_2u_2 = (m_1 + m_2)v_1$ 500 v = 1000 = 0.5 m/s $50 \times 10 + 950 \times 0 = (50 + 950) \times v$ 1 1 1 $KE = 2 m_1 u_{21} = 2 \times 50 \times (1000)_2 = 25 \times 10_6 \text{ erg}$ $\therefore \text{ Loss in } KE = 2 m_1 u_{21} - 2 (m_1 + m_2) v_2$ Initial $= 2 \times 50 \times (1000)_2 - 2 (50 + 950) \times (50)_2 = 25 \times 10_6 - 1250 \times 1000 = 25 \times 10_6 - 1.25 \times 10_6$ ΔK $\frac{\Delta K}{\kappa} \times 100\% = \frac{23.75 \times 10^6}{25}$ ×100 25×10^{6} $= 23.75 \times 10_6 \text{ erg}$ % loss in KE = = 95.00% *:*.. $mv\sqrt{2} = 4mV_1$ 27.

$$V_1 = \frac{v\sqrt{2}}{4} = \frac{v}{2\sqrt{2}}.$$

28. use m₁v₁ = m₂v₂ =P

F.E. =
$$\frac{1}{2} m_{V12} + \frac{1}{2} m_{2V22} = \frac{1}{2} m_1 \left(\frac{P}{m_1}\right)^2 + \frac{1}{2} m_2 \left(\frac{P}{m_2}\right)^2 = \frac{1}{2} \frac{P^2(m_2 + m_1)}{m_1 m_2}$$
.

- 2R
- **29.** If we treat the train as a ring of mass 'M' then its COM will be at a distance π from the centre of the circle. Velocity of centre of mass is :

$$\frac{2R}{\pi} \cdot \frac{\sqrt{R}}{\pi} \cdot \frac{\sqrt{R}}{R} = \frac{2MV}{\pi}$$
As the linear momentum of any system = MVcM

$$\frac{2WV}{\pi} = \frac{2WV}{\pi} = \frac{2MV}{R} = \frac{2MV}$$





38. Equate the momenta of the system along two perpendicular axes. Let u be the velocity and θ the direction of the third piece as shown.

Equating the momenta of the system along OA and OB to zero, we get

 $m \times 30 - 3m \times v \cos \theta = 0 \qquad \dots \dots (i)$ and $m \times 30 - 3m \times v \sin \theta = 0 \qquad \dots \dots (ii)$ These give $3mv \cos \theta = 3 mv \sin \theta$ or $\cos \theta = \sin \theta \qquad \therefore \qquad \theta = 45^{\circ}$ Thus, $\angle AOC = \angle BOC = 180^{\circ} - 45^{\circ} = 135^{\circ}$ Putting the value of θ in Eq. (i) we get $30 m = 3mv \cos 45^{\circ} = \frac{3mv}{\sqrt{2}} \qquad \therefore \qquad v = 10\sqrt{2} m/s$

The third piece will go with a velocity of $10\sqrt{2}$ m/s in a direction making an angle of 135° with either piece.

39. For a exploding body, linear momentum is conseved. From conservation of linear momentum,

 $\begin{array}{rl} P_{\text{initial}} = P_{\text{final}} \\ 0 = m_1 v_1 - m_2 v_2 \\ \text{or} & m_1 v_1 = m_2 v_2 & \dots \dots (i) \\ & \frac{v_1}{v_2} = \frac{m_2}{m_1} & \dots \dots (ii) \end{array}$

$$\frac{E_1}{E_2} = \frac{\frac{1}{2}m_1v_1^2}{\frac{1}{2}m_2v_2^2} = \frac{m_1}{m_2} \times \left(\frac{m_2}{m_1}\right)^2 = \frac{m_2}{m_1}$$

Thus, ratio of kinetic energies

Note: In a collision of two bodies whether it is perfectly elastic or inelastic, linear momentum is always conserved but kinetic energy need not be conserved.

40. Kinetic energy is given by

1 1 $E = 2 mv_2 = 2m (mv)_2$ p^2 $p = \sqrt{2mE}$ E = 2mor but mv = momentum of the particle = p ÷ m_1E_1 p₁ Therefore, $\overline{p_2} = \sqrt{m_2 E_2}$ but it is given that, $p_1 = p_2$ $\therefore \mathbf{m}_1 \mathbf{E}_1 = \mathbf{m}_2 \mathbf{E}_2$ E₁ m_2 or $E_2 = m_1$(i) Now $m_1 > m_2$ m_1 or $m_2 > 1$(ii) Thus, Eqs. (i) and (ii) give E_1 E_2 < 1 $E_1 < E_2$. or The linear momentum of exploding part will remain conserved. Applying conservation of linear momentum, we write $m_1u_1 = m_2u_2$ Here, $m_1 = 18 \text{ kg}$, $m_2 = 12 \text{ kg}$ 18×6

 $\mu_{1} = 6 \text{ ms}_{-1}, u_{2} = ? \qquad \therefore \qquad 18 \times 6 = 12u_{2} \implies \qquad u_{2} = \boxed{12} = 9 \text{ ms}_{-1}$ Thus, kinetic energy of 12 kg mass $\frac{1}{K_{2}} = \frac{1}{2} \prod_{m_{2}u_{22}} \frac{1}{2} \times 12 \times (9)_{2} = 6 \times 81 = 486 \text{ J}$

42. Key Idea : In the given problem conservation of linear momentum and energy hold good. Conservation of momentum yields.

41.

- $m_1v_1 + m_2v_2 = 0$ $4v_1 + 0.2 v_2 = 0$ or(i) Conservation of energy yields 1 1 $\overline{2} m_1 v_{12} + 2 m_2 v_{22} = 1050$ 1 1 $\overline{2} \times 4v_{12} + \overline{2} \times 0.2 \times v_{22} = 1050$ or $2 v_{12} + 0.1 v_{22} = 1050$(ii) or Solving Eqs. (i) and (ii), we have $v_2 = 100$ m/s
- 44. If kinetic energy of system is zero, then momentum of system is necessarily zero.
- 45. By conservation of linear momentum $P_i = P_f \implies 0 = 12 \times 4 + 4 \times v \implies v = 12 \text{ m/s}$ So, kinetic energy of other mass is $\frac{1}{2} \text{ mv}_2 = \frac{1}{2} \times 4(12)_2 = 288 \text{ J}$,
- 46. By conservation of linear momentum

$$0.5 \times 2 = (1.5)v \Rightarrow v = \frac{2}{3} \text{ m/s} \Rightarrow \Delta K = K_i - K_f = \frac{1}{2} \times 0.5 \times (2)_2 - \frac{1}{2} \times 1.5 \left(\frac{2}{3}\right)^2 = 0.67 \text{ J}$$

- **47.** When the centre of mass remains at rest, it is possible that different individual forces do individual works though the net resultant force is zero. As work is a scalar quantity, they gets added up. Also, $\Sigma F_{\text{ext}} = 0 \implies a_{\text{CM}} = 0.$
- **48.** For the momentum to remain conserved all the fragments should finally move in a single plane as for three vectors to give a resultant = 0, they should form a triangle.
- **49.** Since $\Sigma^{F_{ext}} = \vec{0}$ \therefore Moment of system will remain conserved, equal to zero.
- **50.** By momentum conservation $mv + M(0) = (m + M) v' \Rightarrow v' = \frac{mv}{m + M}$
- **51.** mV × N = (Nm + M) V'

SECTION (D)

10. by energy conservation $\frac{1}{2} mv_2 = \frac{1}{2} (2m) \left(\frac{v}{2}\right)^2 + \frac{1}{2} kx_2 \Rightarrow x = \sqrt{2mK}$ SECTION (E)

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3. Area of F-t curve = A = Impulse.

Impulse = dP = A = mv - 0
$$\therefore v = \frac{7}{M}$$
.
5. $\Delta P = P_f - P_i = (-Mv) - (Mv) = -2Mv$
7. $v_1 = \sqrt{2gh} = \sqrt{2 \times 10 \times 10} = 10\sqrt{2} \implies k_2 = \frac{1}{4} k_1 \Rightarrow v_{22} = \frac{1}{4} v_{12} \therefore v_2 = \frac{v_1}{2} = 5\sqrt{2}$

$$|\Delta P| = |-mv_2 - (mv_1)| = m|-v_2 - v_1|$$

$$|\Delta P| = 50 \times 10_{-3} \times \frac{3}{2} \times 10\sqrt{2} = \frac{15 \times 10^{-2}}{\sqrt{2}}$$

$$J = \Delta P = 1.05N-s.$$

8. Impulse = $\int F dt$ = Area under curve = $\frac{1}{2}$ (2) (2) = 2 kg-m/sec.

9. The force imparted by the bali is equal to rate of change of linear momentum.

The vector $\overset{\bigcirc}{OA}$ represents the momentum of the ball before the collision and the vector $\overset{\bigcirc}{OB}$ that after the collision. The vector $\overset{\bigcirc}{AB}$ represents the change in momentum of the ball $\overset{\bigcirc}{\Delta p}$.



As the magnitue of $\stackrel{\square}{OA}$ and $\stackrel{\square}{OB}$ are equal the components of $\stackrel{\square}{OA}$ and $\stackrel{\square}{OB}$ along the wall are equal and in the same direction while those perpendicular to the wall are equal and opposite. Thus, the change in momentum id due only to the change in direction of the perpendicular components.

Hence $\overline{\Delta p}$ = OA sin 60° - (-OB sin 60°) = mv sin 60° + mv sin 60° = 2mv sin 60° = 2 × 3 × 100 × $\frac{\sqrt{3}}{2}$ = 300 $\sqrt{3}$ kg-m/s The force exerted on the wall $\overline{\Delta p}$ 300 $\sqrt{3}$

$$F = \frac{\Delta p}{\Delta t} = \frac{300\sqrt{3}}{0.2} = 1500\sqrt{3} \text{ N}$$
 Note : $\frac{\Box T}{\Delta p}$ is directed perpendicular and away from the plate.

For the duration of collision
 Impulse = change in momentum
 Speeds of both the balls are same just before the collision with ground. (:: v₂ = 2gh)

For elastic collision of first ball with ground velocity of first ball is reversed

$$I_{1} = mv - mu = m(-u) - mu = 2mu$$
For the second ball
$$\vec{I}_{2} = 0 - m\vec{u} = \frac{\vec{I}_{1}}{2} \implies I_{2} = \frac{\vec{I}_{1}}{2}$$

12. Impulse = change in momentum

$$\pi F_0 T$$

 $\frac{\frac{\pi_0}{4}}{4} = mu - 0 \qquad \Rightarrow \qquad u = \frac{\frac{\pi_0}{4}}{4m}$

13.
$$F_x = \frac{\Delta P_x}{\Delta t} = \frac{(Pf_x - Pi_x)}{\Delta t} = \frac{-mV\sin 60^\circ - (mV\sin 60^\circ)}{2 \times 10^{-3}} = -250\sqrt{3} \text{ N}$$
 = $\frac{250\sqrt{3}}{N}$ towards left

14. $|(m_1 \vec{v'_1})|$



= | External force on the system | x time interval = $(m_1 + m_2) g(2 t_0) = 2(m_1 + m_2) gt_0$

SECTION (F)

3. Velocity of heavy mass donot change after collison

$$\frac{v_2 - v_1}{u_2 - u_1} = -e = -1 \qquad \Rightarrow \qquad \frac{v_2 - v}{0 - v} = -1 \qquad \Rightarrow \qquad v_2 = 2v$$

4. If mass = m first ball will stop \Rightarrow v = 0 so k.e. = 0 (min) In other cases there will be some kinetic energy (K.E. can't be negative) 5.

| velocity of separation |

| velocity of approach | e = For elastic collision e = 1|Velocity of separation| = |velocity of approach| For inelastic collision e < 1So |velocity of separation| < |velocity of approach|

6.
$$v_1 = \frac{(m_1 - em_2)u_1}{m_1 + m_2} + \frac{m_2(1 + e)u_2}{m_1 + m_2} = \frac{(m - e2m)u_1}{m + 2m} + \frac{2m(1 + e) \times 0}{m + 2m} = 0 \Rightarrow 0 = m - e2m \Rightarrow e = 1/2$$

7. $mu = mv_1 + mv_2$(i) $u = V_1 + V_2$(i) As solving have $\frac{v_1}{v_2} = \left(\frac{1-e}{1+e}\right)$ $v_{2} - v_{1}$ u(ii)

= e

- $\frac{\frac{1}{2}m(v_{f})^{2}}{\frac{1}{2}m(v_{i})^{2}}$ 0.05
- $=(10-2)^2 = 10-4.$ 27. $0.5 \times v_{P} + m \times 0 = 5.05 v$
- 28. mv = (100 m) u by conservation of linear momentum Pi = Pf ⇒ ⇒ u = v/100
- 30. Kinetic energy remains conserved in elastic collision
- 31. When $M_1 = M_2$, velocity are exchanged. So total energy of M_1 is transfred to M_2

 $mv\hat{i} + mv\hat{j} = 2 m u^{-1}$ By conservation of linear momentum $P_i = P_f$ 32. $\left| \overrightarrow{u} \right| = \frac{v}{\sqrt{2}} = \frac{45\sqrt{2}}{\sqrt{2}} = 45$ $\vec{u} = \frac{v}{2}(\hat{i} + \hat{j})$ ⇒

velocity of seperation

- Velocities will be interchanged 34.
- $V_2 V_1$ $\frac{4 - v_1}{4 - 6} = -1$ We have $\overline{u_2 - u_1} = -e$ 35. ⇒ (velocity of heavier mass will not change) $4 - v_1 = 2$ $v_1 = 2 \text{ m/s}$ vsin0 vsin0 V V vcosθ vcosθ 37. after collision
 - be fore collision So angle between velocity vectors is 90°
- 40. In an inelastic collision, the particles do not regain their shape and size completely after collision. Some fraction of mechanical energy is retained by the colliding particles in the form of deformation potential energy. Thus, the kinetic energy of particles no longer remains conserved. However, in the absence of external forces, law of conservation of linear momentum still holds good.

Centre of Mass

Given, $m_1 = 20 \text{ kg}$, $u_1 = 10 \text{ m/s}$,

 $m_2 = 5 \text{ kg}, u_2 = 0$ Using law of conservation of momentum, $m_1u_1 + m_2u_2 = (m_1 + m_2)v$ 200 v = 25 = 8 m/s $20 \times 10 + 5 \times 0 = (20 + 5) \times v$... 1 1 Kinetic energy of the composite mass = $\frac{1}{2}$ (m₁ + m₂) v₂ = $\frac{1}{2}$ (20 + 5) × (8)₂ = 25 × 32 = 800 J 42. During a perfectly elastic collision both energy and momentum are conserved

41.

When deformation is maximum both the particles are moving with same velocity. So applying momentum conservation.

$$m_{1}v_{1} + m_{2}v_{2} = m_{1}v_{1'} + m_{2}v_{1'} \implies v_{1'} = \frac{m_{1}v_{1} + m_{2}v_{2}}{m_{1} + m_{2}}$$
Applying energy conservation:

$$\frac{1}{2} \prod_{m_{1}v_{12}} \frac{1}{2} \prod_{m_{2}v_{22}} \frac{1}{2} (m_{1} + m_{2}) (v_{1'})_{2} + \Delta U_{deformation}$$

$$\Rightarrow \Delta U_{deformation} = \frac{1}{2} \frac{m_{1}m_{2}}{(m_{1} + m_{2})} \times (v_{1} - v_{2})_{2} = \frac{100}{3} \implies v_{1} - v_{2} = 10 \text{m/sec.}$$
Let the velocities of plank and body of mass $\frac{m_{1}}{2}$

48. Let the velocities of plank and body of mass

move with speed V₁ and V₂ after collision as shown.

$$\begin{array}{c|c}
\hline m & V_1 \\
\hline m & V_2 \\
\hline Plank \\
From conservation of momentum. \\
\hline mv - \frac{m}{2} & 2v = mv_1 + \frac{m}{2} & v_2 \\
\hline or & 2v_1 + v_2 = 0 \\
\hline or & 2v_1 + v_2 = 0 \\
\hline From equation of coefficient of restitution. \\
\hline e = 1 = \frac{v_2 - v_1}{v + 2v} \Rightarrow v_2 - v_1 = 3v \\
\hline v_1 = -v \\
\hline \end{array}$$
(1)



Velocity of Seperation = Velocity of approach (collision is elastic) \therefore V – 5 = 20 + 5 \Rightarrow V = 30 m/s

2d

49.

50. $t = V_0$ (time for successive collision)

$$N \times t = dP = mv_0 - (-mv_0) \qquad \Rightarrow \qquad N \times \frac{2d}{v_0} = 2mv_0$$

52. According to Newton's Law

$$\frac{v_2 - v_1}{2}$$

$$e = u_1 - u_2$$

For elastic collision cofficient of restitution e = 1 so

$$V_2 - V_1 = u_1 - u_2$$
 Statement - 1 is correct

Linear momentum is conserved in both elastic & non elastic collision but it's not the explanation of statement -1 so it is not the correct explanation of the statement A. **Ans. (2)**

- 54. Max potential energy of deformation = max. K.E. loss = $\frac{1}{2} \times 3 \times 22 + \frac{1}{2} \times 2 \times 32 = 15$ J
- **55.** All energy is transfered to other particles.

56.
$$V_{A} = \left(\frac{m_{1} - m_{2}}{m_{1} + m_{2}}\right) u_{1} + \frac{2m_{2}u_{1}}{m_{1} + m_{2}} = \left(\frac{10 - 38}{10 + 38}\right) 15 + \frac{2 \times 38 \times 3}{10 + 38} = -4 \text{ m/s}.$$

- **57.** (Easy) Nothing is mentioned about coefficient of restitution. Hence the only true statement is 'their final velcities may be zero.'
- 60. Velocity before collision with surface is $\sqrt{2gh} = \sqrt{2g1}$ velocity after collision with surface is e x $\sqrt{2gh} = 0.6 \times \sqrt{2 \times 10 \times 10}$ $(e\sqrt{2gh})^2$

Hight reached by ball after collision h = $\frac{2g}{2}$ = 0.36 m

SECTION (G)

1.
$$F = \mu \frac{dm}{dt} \Rightarrow 210 = 300 \times \frac{dm}{dt} \Rightarrow \frac{dm}{dt} = 0.7 \text{ kg/s}.$$

- 8. Let Initial thrust of the blast be F then F mg = ma F = m (g + a) = $3.5 \times 104 \times (10 + 10) = 7 \times 105$ N
- 9. Neglecting gravity,

$$v = u \ell n \left(\frac{m_0}{m_t} \right);$$

u = ejection velocity w.r.t. balloon. m₀ = initial mass m_t = mass at any time t.
$$= 2\ell n \left(\frac{m_0}{m_0 / 2} \right) = 2\ell n 2.$$

EXERCISE # 2

1. Taking C as origin and x & y-axes as shown in figure. Due to symmetry about y-axis $x_{cm} = 0$



4. Let at O there will be a collision. If smaller sphere moves x distance to reach at O, then bigger sphere will zmove a distance of

$$F = \frac{GM \times 5M}{(12R - x)^2} \implies a_{small} = \frac{F}{M} = \frac{G \times 5M}{(12R - x)^2}$$

$$a_{big} = \frac{F}{5M} = \frac{GM}{(12R - x)^2} \implies x = \frac{1}{2} a_{small} t_2$$

$$= \frac{1}{2} \frac{G \times 5M}{(12R - x)^2} t^2 \qquad \dots \dots \dots (i)$$

$$(9R - x) = \frac{1}{2} a_{big} t_2 \qquad = \frac{1}{2} \frac{GM}{(12R - x)^2} t^2 \dots \dots \dots (ii)$$

Thus, dividing Eq. (i) by Eq. (ii), we get $\therefore \frac{9R - x}{2} = 5 \Rightarrow x = 45R - 5x \Rightarrow 6x = 45R \Rightarrow x = 7.5R$

Centre of Mass

Velocity of particle after 5 s v = u - gt v = 100 - 10 x 5 = 100 - 50 = 50 m/s (upwards) Conservation of linear momentum gives Mv = $m_1v_1 + m_2v_2$ (i) Taking upward direction positive, the velocity v_1 will be negative. $\therefore v_1 = -25$ m/s, v = 50 m/s Also M = 1 kg, $m_1 = 400$ g = 0.4 kg and $m_2 = (M - m_1) = 1 - 0.4 = 0.6$ kg Thus, Eq. (i) becomes, $1 - 50 = 0.4 \times (-25) + 0.6 v_2$ 60

or $50 = -10 + 0.65 v_2$ or $0.6 v_2 = 60$ or $v_2 = \overline{0.6} = 100 \text{ m/s}$ As v_2 is positive, therefore the other part will move upwards with a velocity 100 m/s.

9.

6.

before collision



after collision

 $\upsilon_x = \upsilon$

In x-direction $mv + 0 = 0 + mv_x \Rightarrow$ In y-direction

4

4

 $M_A = \rho \times \frac{3}{\pi r_3}$

: Velocity of second mass after collision

$$M_{B} = \rho \times \frac{3}{3} \pi (2r)_{3} = 8M_{A}$$

$$m_{A} \vee + 0 = m_{A} \vee 1 + m_{B} \vee 2 \qquad \dots \dots (i)$$

$$e \vee = \vee 2 - \vee 1 \qquad \qquad \dots \dots (ii)$$
Adding (i) + (ii) = $9 \vee 2 = \vee + \frac{\sqrt{2}}{2} = \frac{3 \vee}{2}$

$$\therefore \vee 1 = \vee 2 - \frac{\sqrt{2}}{2} = \frac{\sqrt{6}}{6} - \frac{\sqrt{2}}{2} = -\frac{\sqrt{3}}{3} \qquad \therefore \qquad \frac{\sqrt{1}}{\sqrt{2}} = \frac{\sqrt{3}}{\sqrt{6}} = 2.$$

 $e = \frac{1}{2}$

10.* $\vec{P_1} = p\hat{i}$

$$\vec{P_2} = -p\hat{i}$$
 as there is no external force so momentum will remain conserved

$$\vec{P_1' + \vec{P_2'}} = \vec{P_1 + \vec{P_2}}$$

$$\vec{P_1' + \vec{P_2'}} = 0$$
 Now from option

$$(1) \vec{P_1' + \vec{P_2'}} = (a_1 + a_2)\hat{i} + (b_1 + b_2)\hat{j} + c_1\hat{k}$$

$$(2) \vec{P_1' + \vec{P_2'}} = (c_1 + c_2)\hat{k}$$

$$(3) \vec{P_1' + \vec{P_2'}} = (a_1 + a_2)\hat{i} + (b_1 + b_2)\hat{j}$$

$$(4) \vec{P_1' + \vec{P_2'}} = (a_1 + a_2)\hat{i} + 2b_1\hat{j}$$
 and it is given that $a_1 b_1 c_1$, $a_2, b_2, c_2, \neq 0$ in case of A and D it is not
possible to get $\vec{P_1' + \vec{P_2'}} = 0$. Hence **Ans. (1) and (4)**

EXERCISE # 3 PART - I

1. Apply law of conservation of linear momentum. Momentum of first part = $1 \times 12 = 12$ kg ms₋₁ Momentum of the second part = $2 \times 8 = 16$ kg ms₋₁

∴ Resultant momentum = $\sqrt{(12)^2 + (16)^2}$ = 20 kg ms₋₁ The third part should also have the same momentum. Let the mass of the third part be M, then 4 × M = 20 M = 5 kg.

2. Here, $m_1 = m$, $m_2 = 2m$

u₁ = 2 m/s, u₂ = 0 coefficient of restitution, e = 0.5 Let v₁ and v₂ be their respective velocities after collision. Applying the law of conservation of linear momentum, we get m₁u₁ + m₂u₂ = m₁v₁ + m₂v₂ ∴ m × 2 + 2m × 0 = m × v₁ + 2m × v₂ or 2m = mv₁ + 2mv₂ or 2 = (v₁ + 2v₂) ...(i) By definition of coefficient of restitution, $\frac{v_2 - v_1}{v_1 - v_1}$

 $\begin{array}{l} e = \begin{tabular}{ll} u_1 - u_2 & or & e(u_1 - u_2) = v_2 - v_1 \\ 0.5(2 - 0) = v_2 - v_1 & ...(ii) \\ 1 = v_2 - v_1 & Solving equations (i) and (ii), we get \\ v_1 = 0 \ m/s, v_2 = 1 \ m/s \end{array}$

3. As no external force is acting on the system, the centre of mass must be at rest i.e. $v_{CM} = 0$.

4.
$$m \xrightarrow{0} \nu x \xrightarrow{0} 3m$$

From momentum conservation $m\upsilon\hat{i} + 3m(2\upsilon)\hat{j} = (4m)\vec{\upsilon}$

$$\vec{\upsilon} = \frac{\upsilon}{4}\hat{i} + \frac{6}{4}\upsilon\hat{j} = \frac{\upsilon}{4}\hat{i} + \frac{3}{2}\upsilon\hat{j}$$



5.

There is no external force so com will not shift

6. m_2 m₁ $(\mathbb{B}) \to v$ (A) u = 0conservation of linear momentum along x direction $m_2 v = m_1 v_x$ $m_2 v$ 1 $m_1 = v_x$ along y direction $m_2 \times 2 = m_1 v_y$ $\tan \theta = 2$ Ans. 4 $300 \times (0) + 500(40) + 400 \times 70$ 300 + 500 + 4007. $X_{cm} =$

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13. During the collision, apply moementum conservation

 $(0.01)(400) + 0 = (2)V + (0.01)V' \text{ where } V = \sqrt{2gh}$ $V = \sqrt{2 \times 10 \times 0.1}$ $V = \sqrt{2} \text{ solving } V' = 120 \text{ m/sec. Ans.}$ Mass of balls are same and the collision is perfect

14.Mass of balls are same and the collision is perfectly elastic, so their velocity will be interchanged.So. $V_A = -0.3$ m/s, $V_B = 0.5$ m/sAns.

S0,
$$V_A = -0.3 \text{ m/s}$$
, $V_B = 0.5 \text{ m/s}$

15. From momentum conservation

mu + 0 = 0 + (4m) V₂
$$\Rightarrow$$
 V₂ = $\frac{u}{4}$
e = $\frac{V_2}{u} = \frac{u_4}{u} = \frac{1}{4} = 0.25$

16. Energy transfered to B initial energy of B = zero Final velocity of

$$V_{B} = \left(\frac{M_{2} - M_{1}}{M_{1} + M_{2}}\right)u_{2} + \frac{2M_{1}u_{1}}{M_{1} + M_{2}}$$
$$M_{1} = 4M u_{1} = u$$
$$M_{2} = 2M u_{2} = 0$$

$$V_{B} = \frac{2(4M)u}{6M} = \frac{4}{3}u \qquad \Rightarrow \qquad \frac{\frac{1}{2}M_{2}V_{B}^{2}}{\frac{1}{2}M_{1}u_{1}^{2}} = \frac{\frac{1}{2}2M\left(\frac{4}{3}\right)^{2}u^{2}}{\frac{1}{2}4Mu^{2}}$$
Fraction of energy lost $= \frac{8}{9}$

17. Momentum conservation
$$p_i = p_f$$

 $5m(0) = mv\hat{i} + mv(\hat{j}) + 3mv_1 \Rightarrow -(v\hat{i} + v\hat{j}) = 3v_1$
 $v_1 = \frac{-(v\hat{i} + v\hat{j})}{3}, v_1 = \frac{\sqrt{2v}}{3}$
Energy released is
 $E = \frac{1}{2}mv^2 + \frac{1}{2}mv^2 + \frac{1}{2}3m\left(\frac{\sqrt{2}v}{3}\right)^2 \Rightarrow E = mv^2 + \frac{mv^2}{3} \Rightarrow E = \frac{4}{3}mv^2$
PART - III

1. Since masses of particles are equal, collisons are elastic, so particles will exchange velocities after each collision. The first collision will be at a point P and second at point Q again and before third collision the particles will reach at A.



2. If initial momentum of particles is zero, then they loss all their energy in inelastic collision but here initial momentum is not zero.

Principle of conservation of momentum holds good for all collision.

3.
$$R = \frac{u\sqrt{\frac{2h}{g}}}{20} \Rightarrow 20 = \frac{V_1\sqrt{\frac{2\times5}{10}}}{10} \text{ and } 100 = \frac{V_2\sqrt{\frac{2\times5}{10}}}{10} \Rightarrow V_1 = 20 \text{ m/s}, V_2 = 100 \text{ m/sec.}$$

Applying momentum conservation just before and just after the collision $(0.01) (V) = (0.2)(20) + (0.01)(100) \Rightarrow$ V = 500 m/s \mathbf{P}^2 \mathbf{P}^2 Maximum energy loss = $\frac{1}{2m} - \frac{1}{2(m+M)}$ 4. $= \frac{P^2}{2m} \left[\frac{M}{(m+M)} \right] = \frac{1}{2}mv^2 \left\{ \frac{M}{m+M} \right\} \quad \left(f = \frac{M}{m+M} \right)$ Hence Statement -1 is wrong and statement 2 is correct Hence 5. At the highest point $\sqrt{u_0^2 - 2gH}$ →u₀cosα m after collision before collision $u_0 \cos \alpha$ 2 (by applying momentum conservation in horizontal direction) $V_1 =$ $u_0^2 \sin^2 \alpha$ $u_0 \cos \alpha$ 2g 2 (by applying momentum conservation in vertical direction) (H =) θ = 45° V2 = t = 0 (Before collision) v = qt6. mg²t² $K = \overline{2}$ $K \propto t^2$: parabolic graph then during collision kinetic energy first decreases to elastic potential energy and then increases. Most appropriate graph is B. lust before collision lust after collision 7.

$$(m) \rightarrow 2V$$
Energy loss $\Delta E = \frac{1}{2} m (2V)_2 + \frac{1}{2} (2m) V_2 - \frac{1}{2} (3m) 2 \left(\frac{2V}{3}\right)^2 = 3mV_2 - \frac{4mV^2}{3} = \frac{5mV^2}{3} = 55.55\%$

$$\frac{h}{4}$$

8. COM of uniform solid cone of height h is at height 4 from base, therefore from vertex its 4

9. Case-I



