	Exercise	.1		
			N CORRECT TYPE	
SECT	ION (A) : KINEMAT	ICS		
1.	If angular displacemen sec, the angular velocit (1) 1.5	t of a particle moving on y at t = 2 sec, will be (2) 2.5	a curved path be given (3) 9.5	as, $\theta = 1.5 \text{ t} + 2t_2$, where t is in (4) 8.5
2.	A wheel starts rotating seconds. The total ang (1) 60	from rest (with constan ular displacement in radia (2) 80	t α) and attains an ang ans will be (3) 100	ular velocity of 60 rad/sec in 5 (4) 150
3.	All the particles of a rig (1) Passing from any p (3) Passing from any p	id body in a rotatory motio oint inside the object oint	on have axis of rotation: (2) Passing from any po (4) Passing from centre	pint outside the object of mass of object
4.	A wheel has angular ao has rotated through an (1) 6	cceleration of 3.0 rad/s₂ a angle (in radian) of (2) 10	nd an initial angular spe (3) 12	ed of 2.0 rad/s. In a time of 2s it [RPMT-2008] (4) 4
5.	A fan is running at 3000 in 10 seconds. The tota (1) 150) rpm. It is switched off. It al number of revolution in (2) 250	comes to rest by uniform this period. (3) 350	nly decreasing its angular speed (4) 300
6.	A block hangs from a s in a horizontal position the block going down a (1) 4 m/s	tring wrapped on a disc o . If the angular speed of t that instant? (2) 3 m/s	f radius 20 cm free to ro the disc is 10 rad/s at so (3) 2 m/s	tate about its axis which is fixed ome instant, with what speed is (4) 5 m/s
7.	A sphere is rotating ab (1) The particle on the (2) The particles on the (3) Different particles of (4) All the particles on the	out a diameter. surface of the sphere do n diameter mentioned abo n the surface have differe the surface have same lin	not have any linear acce we do not have any linea ent angular speeds. lear speed	leration ar acceleration
SECT	ION (B) : MOMENT	OF INERTIA		
1.	A stone of mass 4kg is inertia of the stone abo	whirled in a horizontal ci	ircle of radius 1m and m	akes 2 rev/sec. The moment of
	(1) 64 kg \times m ₂	(2) 4 kg × m_2	(3) 16 kg × m ₂	(4) 1 kg × m ₂
2.	Two spheres of same n about its diameter is I, point would be	nass and radius are in cor then the moment of inertia	ntact with each other. If th a of both the spheres abo	ne moment of inertia of a sphere out the tangent at their common
	(1) 3 I	(2) 71	(3) 4 I	(4) 5 I
3.	From the theorem of period (1) $I_x - I_y = I_z$	erpendicular axes. If the la (2) I _x + I _z = I _y	amina is in X- Y plane (3) I _x + I _y = I _z	(4) $I_y + I_z = I_x$
4.	The moment of inertia (1) mass only (3) distribution of partic	of a body depends upon les only	(2) angular velocity only(4) mass and distribution	, n of mass about the axis
5.	A wheel of mass 10 kg be	has a moment of inertia c	f 160 kg m₂ about its ow	n axis, the radius of gyration will [Pb. PMT 2001]
6.	(1) 10 mAnalogue of mass in ro(1) Moment of inertia	(2) 8 m taional motion is (2) Angular momentum	(3) 6 m (3) Torque	(4) 4 m [DCE 2000, 01] (4) None of these

7.	The moment of inertia o	f a uniform ring of mass	M and radius r about a t	angent lying in its own plane is [MP PMT 1997; RPET 2001]
		3		1
	(1) 2Mr ₂	(2) $\overline{2}_{Mr_2}$	(3) Mr ₂	(4) 2 Mr ₂
8.	Three rings each of mas the system about YY' w	ss M and radius R are a ill be	rranged as shown in the	figure. The moment of inertia of [MP PET 2000]
			Y'	
		2	I	7
	(1) 3 MR ₂	(2) $\frac{3}{2}$ MR ₂	(3) 5 MR ₂	(4) $\frac{7}{2}$ MR ₂
9.	Radius of gyration of a l (1) Mass and size of bo (3) Size of body	oody depends on dy	(2) Mass distribution an (4) Mass of body	[RPET 2000] Id axis of rotation
10.	The moment of inertia o (1) In motion along a cu (3) In rotational motion	f body comes into play rved path	(2) In linear motion (4) None of the above	[AFMC-1979]
11	Moment of inertia of a perpendicular to the pla (1) 1/2 MR ₂	ring of mass M and ra ne is (2) MR ₂	adius R about an axis p (3) 1/4 MR ₂	assing through the centre and [CPMT-1982] (4) 3/4 MR ₂
12	The moment of inertia of length and passing thro (1) Ml ₂ /12	of a straight thin rod of ugh its one end, is (2) Ml ₂ /3	mass M and length I ab [RPMT 1996; M (3) Ml ₂ /2	out an axis perpendicular to its IPPMT 1996; MPPET 2002] (4) Ml ₂
13.	Three rods each of leng each of the rod is at the $\frac{2ML^2}{3}$	th L and mass M are plat origin. The moment of i $\frac{4ML^2}{3}$	aced along X. Yand Z axe nertia of this system above $\frac{5ML^2}{3}$	tes in such a way that one end of ut Z axis is [AMU 1995] $\frac{ML^2}{3}$
14.	Three point masses eac the moment of inertia of	ch of mass m are placed this system about an a	l at the corners of an equ xis passing along one sid	ilateral triangle of side 'a'. Then e of the triangle is
	(1) ma ₂	(2) 3 ma ₂	(3) 3/4 ma ₂	[AIIMS 1995] (4) 2/3 ma₂
15.	The moment of inertia o at a distance of L/3 on t $\frac{7ML^2}{48}$	f a uniform thin rod of length from one of its error $\frac{ML^2}{Q}$	high L and mass M about and perpendicular to $\frac{ML^2}{42}$	an axis passing through a point the rod is [PMT 1995] $\frac{ML^2}{2}$
	(1) 40	(2) 9	(3) 12	(4) 3
16.	Two rings have their more ratio of their masses wil (1) 2 : 1	oments of inertia in the l be (2) 1 : 2	ratio 2 : 1 and their diam (3) 1 : 4	eters are in the ratio 2 : 1. The [MP PMT/PET 1998] (4) 1 : 1

17. Four thin rods of same mass M and same length *l*, form a square as shown in figure. Moment of inertia of this system about an axis through centre O and perpendicular to its plane is **[MP PMT 2002]**



18. Two spheres each of mass M and radius R/2 are connected with a massless rod of length 2R as shown in the-figure. What will be the moment of inertia of the -system about an axis passing through the centre of one of the spheres and perpendicular to the rod [Raj. PMT 1996]



19. The moment of inertia of a disc of mass M and radius R about a tangent to its rim in its plane is : [AIPMT-1999]

(1)
$$\frac{2}{3}_{MR_2}$$
 (2) $\frac{3}{2}_{MR_2}$ (3) $\frac{4}{5}_{MR_2}$ (4) $\frac{5}{4}_{MR_2}$

20. If the moment of inertia of a disc about an axis tangential and parallel to its surface be I, then what will be the moment of inertia about the axis tangential but perpendicular to the surface[Raj. PET 1996]

$$(1) \frac{6}{5} I \qquad (2) \frac{3}{4} I \qquad (3) \frac{3}{2} I \qquad (4) \frac{5}{4} I$$

21. The moment of inertia of a sphere of mass M and radius R about an axis passing through its centre is $\frac{2}{-MR^2}$

⁵. The radius of gyration of the sphere about a parallel axis to the above and tangent to the sphere is [EAMCET (Engg.) 2000]

$$\frac{7}{5} \mathsf{R} \qquad \qquad \frac{3}{5} \mathsf{R} \qquad \qquad (3) \begin{pmatrix} \sqrt{7} \\ \sqrt{5} \end{pmatrix} \mathsf{R} \qquad \qquad (4) \begin{pmatrix} \sqrt{3} \\ \sqrt{5} \end{pmatrix} \mathsf{R}$$

22. Four particles each of mass m are placed at the corners of a square of side length *l*. The radius of gyration of the system about an axis perpendicular to the square and passing through its centre is

[EAMCET (Med.) 2001]

(1) $\frac{1}{\sqrt{2}}$ (2) $\frac{1}{2}$ (3) I (4) $(\sqrt{2})$ I

(

23.	One circular ring and c moments of inertia abo	one circular disc, both a ut the axes passing thro	re having the same mas ough their centres and pe	s and radius. The ratio of their erpendicular to their planes. will IDCE 20001
	(1) 1 : 1	(2) 2 : 1	(3) 1: 2	(4) 4 : 1
24.	The radius of gyration of gravity and perpendicul	of a disc of mass 100 g a ar to the plane is	and radius 5 cm about ar	n axis passing through centre of [MH CET 2000]
	(1) 3.54 cm	(2) 1.54 cm	(3) 4.54 cm	(4) 2.5 cm
25.	The moment of inertia $\frac{2}{2}$	of a solid sphere about it $\frac{7}{2}$	s tangential axis will be : $\frac{5}{2}$	[RPMT_2004] 2_
	(1) ⁵ MR ₂	(2) ⁵ MR ₂	(3) ³ MR ₂	(4) ³ MR ₂
26.	The moment of inertia i (1) mass	n rotational motion will b (2) velocity	e equivalent to as ir (3) momentum	n linear motion : [RPMT-2004] (4) force
27.	Out of the given bodies passing through its cer (1) Disc of radius a (3) Square lamina of sid	(of same mass) for whi htre of gravity and perpe de 2a	ch the moment of inertia ndicular to its plane? (2) Ring of radius a (4) Four rods of length :	will be maximum about the axis [RPMT-2005] 2a making a square
28.	Five particles of mass 2 Moment of inertia of the to its plane is :	kg are attached to the r system about the axis	rim of a circular disc of ra passing through the centr [RPMT	dius 0.1 m and negligible mass. re of the disc and perpendicular -2006]
	(1) 1 kg m ₂	(2) 0.1 kg m ₂	(3) 2 kg m ₂	(4) 0.2 kg m ₂
29.	If the moment of inertia be the moment of inertia	of a disc about an axis a about the axis tangent	tangential and parallel to ial but perpendicular to th	its surface be I,, then what will ne surface ? [RPMT-2009]
	(1) $\frac{6}{5}$ I	(2) $\frac{3}{4}^{I}$	(3) $\frac{3}{2}^{1}$	(4) $\frac{5}{4}^{I}$
30.	The moment of inertia of the moment of the wire	of a uniform semicircular through the centre is	wire of mass M and radi	us R about a line perpendicular
		$\frac{1}{2}$	$\frac{1}{4}$	$\frac{2}{5}$
	(1) MR ₂	(2) ² MR ₂	(3) ⁴ MR ₂	(4) ⁵ MR ₂
31.	Let I_A and I_B be moment through the centre of m (1) $I_A < I_B$ (3) If the axes are paral	nts of inertia of a body a ass of the body but B do	bout two axes A and B r bes not. (2) If $I_A < I_B$, the axes ar (4) If the axes are not n	espectively, The axis A passes e parallel. arallel la > le
32.	A thin rod of length L a passing through two m inertia about this axis is	Ind mass M is bend at t iddle point O and perpe	he middle point O as sh endicular to the plane of O	own in figure. Consider an axis the bent rod. Then moment of
			θ	
	(1) 2/3 mL ₂	(2) 1/3 mL2	≫ (3) 1/12 mL₂	(4) 1/24 mL ₂
~~	The second second second second			

33. The moment of inertia of a uniform circular disc about its diameter is 200 gm cm₂. Then its moment of inertia about an axis passing through its center and perpendicular to its circular face is

 (1) 100 gm cm₂
 (2) 200 gm cm₂
 (3) 400 gm cm₂
 (4) 1000 gm cm₂

^{34.} Moment of inertia of a uniform disc about OO' is:



35. Three rings each of mass m and radius r are so placed that they touch each other. The radius of gyration of the system about the axis as shown in the figure is :



- **36.** Let ℓ be the moment of inertia of a uniform square plate about an axis AB that passes through its centre and is parallel to two of its sides. CD is a line in the plane of the plate that passes through the centre of the plate and makes an angle θ with AB. The moment of inertia of the plate about the axis CD is then equal to [IIT 1998; JIPMER 2000](1) ℓ (2) $\ell \sin_2 \theta$ (3) $\ell \cos_2 \theta$ (4) $\ell \cos_2 \theta/2$
- **37.** A circular disc is to be made using iron and aluminium. To keep its moment of inertia maximum about a geometrical axis, it should be so prepared that :- [AIPMT_2002]
 - (1) aluminium at interior and iron surrounds it
 - (2) iron at interior and aluminium surrounds it
 - (3) aluminium and iron layers in alternate order
 - (4) sheet of iron is used at both external surfaces and aluminium sheet as inner material
- **38.** Let I be the moment of inertia of a uniform square plate about an axis AB that passes through its centre and is parallel to two of its sides. CD is a line in the plane of the plate that passes through the centre of the plate and makes an angle θ with AB as shown in figure. The moment of inertia of the plate about the axis CD is then equal to



 39. Moment of inertia of a circular wire of mass M and radius R about its diameter is :[AIEEE 4/300 2002] MR²

(1) 2	(2) MR ₂	(3) 2MR ₂	(4)
(1) -	(\mathbf{Z}) IVIT2	$(3) \angle 1011 \sqrt{2}$	(4)

40. The ratio of the radii of gyration of a circular disc about a tangential axis in the plane of the disc and of a circular ring of the same radius about a tangential axis in the plane of the ring is **[AIPMT-2004]**

(1) 2 : 3	(2) 2 : 1	(3) ^{√5} ∶ √6	(4) 1:√2
-----------	-----------	------------------------	----------

41. Three particles, each of mass m grams situated at the vertices of an equilateral triangle ABC of side ℓ cm (as shown in the figure). The moment of inertia of the system about a line AX perpendicular to AB and in the plane of ABC, in gram-cm₂ units will be : [AIPMT_2004]



SECTION (C) : TORQUE

1.	The product of moment (1) force	of inertia and angular ac (2) torque	cceleration is (3) angular momentum	(4) rotational kinetic energy
2.	A disc of radius 2m and be	d mass 200kg is acted u	pon by a torque 100N-m	. Its angular acceleration would
	(1) 1 rad/sec ₂	(2) 0.25 rad/sec ₂	(3) 0.5 rad/sec ₂	(4) 2 rad/sec ₂
3.	Rotational power in rota (1) $\dot{\omega}$. τ	ational motion is (2) $\omega \times \tau$	(3) ^τ . α	(4) $\vec{\tau} \times \vec{\alpha}$
4.	A constant torque of 31. 2, then the moment of in (1) 2.5 kg-m ₂	4 N-m is exerted on a piv nertia of the wheel is (2) 3.5 kg-m ₂	roted wheel. If angular ac (3) 4.5 kg-m ₂	celeration of wheel is 4π rad/see [AIIMS 2001] (4) 5.5 kg-m ₂
5.	A body whose moment displacement of the boo (1) 400 radian	of inertia is 3 kg-m₂ is in dy will be : (2) 200 radian	rest. It is rotated for 20 s (3) 100 radian	ec by a torque of 6 Nm, angular [RPMT_2005] (4) 250 radian
6.	A force $\vec{F} = 4\hat{i} - 10\hat{j}$ co-ordinates on the axis) acts on a body at a poi s of rotation . The torque	nt having position vector acting on the body is :	$-5\hat{i} - 3\hat{j}$ relative to origin of
	(1) 38 k	(2) - 25 k	(3) 62 k	(4) none of these
7.	A force $F = \begin{pmatrix} 2 & \hat{i} + 3 & \hat{j} \\ be: \end{pmatrix}$	$-\hat{k}$ acts at a point (2, -3	3, 1). Then magnitude of	torque about point (0, 0, 2) will
	(1) 6	(2) 3 √5	(3) 6 ^{√5}	(4) none of these
8.	In case of torque of a co (1) Increase	ouple if the axis is chang (2) Decrease	ed by displacing it parall (3) Remain constant	el to itself, torque will :aa (4) None of these
9.	A torque of 30 N-m is a rotating from rest then, (1) 750 rad	acting on a wheel of ma its angular displacement (2) 1500 rad	ass 5 kg and moment of in 10 seconds will be : (3) 3000 rad	inertia 2 kg-m ₂ . If wheel starts [RPMT_2002] (4) 6000 rad
10.	Let \overrightarrow{F} be the force actin the origin. Then : (1) $\overrightarrow{r} \cdot \overrightarrow{F} = 0$ and $\overrightarrow{F} \cdot \overrightarrow{\tau} \neq 1$	ng on a particle having p 0	osition vector \vec{r} and $\vec{\tau}$ is (2) $\vec{r} \cdot \tau \neq 0$ and $\vec{F} \cdot \vec{\tau} = 0$	be the torque of this force about [AIEEE 4/300 2003]
	(3) $\mathbf{r} \cdot \mathbf{\tau} \neq 0$ and $\mathbf{F} \cdot \mathbf{\tau} \neq 0$	J	(4) $\mathbf{r} \cdot \mathbf{\tau} = 0$ and $\mathbf{F} \cdot \mathbf{\tau} = 0$	0
SECT	ION (D) : ROTATION	NAL EQUILIBRIUM		
1.	Four equal and parallel cm and 80 cm respective	forces are acting on a rovely from one end of the	d (as shown in figure) a rod. Under the influence F	t distances of 20 cm, 40 cm, 60 of these forces the rod :
		0 20 40	60 80	

- ♦ F (2) Experiences a torque(4) Experiences a torque and also a linear motion (1) Is at rest (3) Experiences a linear motion
- If a rigid body is subjected to two forces $F_1 = 2i + 3j + 4k$ acting at (3,3,4) and $F_2 = -2i 3j 4k$ acting at (1, 0, 0) then which of the following is (are) true? [REE 94] (1) The body is in equilibrium. (2) The body is under the influence of a couple only. 2.

- (3) The body is under the influence of a single force.
- (4) the body is under the influence of a force together with a couple.

3. A uniform rod of mass m and length L is suspended with two massless strings as shown in the figure. If the rod is at rest in a horizontal position the ratio of tension in the two strings T₁/T₂ is:

4. Two persons of equal height are carrying a long uniform wooden beam of length ℓ . They are at distance ℓ (1) 1: 1 (2) 1: 2 (3) 2: 1 (4) 4: 3 Two persons of equal height are carrying a long uniform wooden beam of length ℓ . They are at distance ℓ (1) 2: 3 (2) 1: 3 (3) 4: 3 (4) 1: 2

5. A block of mass m is held fixed against a wall by applying a horizontal force F. Which of the following option is incorrect. [JEE Scr. 2005, 3/84]



→ ↓
 (2) normal will not produce torque
 (4) normal reaction = F

1

(4) 15

6. A 'T' shaped object with dimensions shown in the figure, is lying on a smooth floor. A force 'F' is applied at the point P parallel to AB, such that the object has only the translational motion without rotation. Find the location of P with respect to C : [AIEEE 4/300 2005]



SECTION (E) : ROTATION ABOUT FIXED AXIS ($\tau_H = I_H \alpha$)

17g

16

(2)

- 1. One end of a uniform rod of mass m and length ℓ is clamped. The rod lies on a smooth horizontal surface and rotates on it about the clamped end at a uniform angular velocity ω . The force exerted by the clamp on the rod has a horizontal component
- **2.** (1) $m\omega_2\ell$ (2) zero (3) mg (4) $2 m\omega_2\ell$ The uniform rod of mass 20 kg and length of 1.6 m is pivoted at its end and swings freely in the vertical plane. Angular acceleration of rod just after the rod is released from rest in the horizontal position.

3. A uniform rod hinged at its one end is allowed to rotate in vertical plane. Rod is given an angular velocity ω in its vertical position as shown in figure. The value of ω for which the force exerted by the hinge on rod is zero in this position is :

(3)

16g

15

15g

16

(1)



5. Two men support a uniform horizontal rod at its two ends. If one of them suddenly lets go, the force exerted by the rod on the other man will:

(3)

 $2l^2$

(4) ma

(1) remain unaffected (2) increase

(2)

- (3) decrease
- (4) become unequal to the force exerted by him on the beam.
- 6. A uniform disc of mass m and radius r and a point mass m are arranged as shown in the figure. The acceleration of point mass is: (Assume there is no slipping between pulley and thread and the disc can rotate smoothly about a fixed horizontal axis passing through its centre and perpendicular to its plane)



SECTION (F): ROTATION ABOUT FIXED AXIS (ENERGY CONSERVATION)

1. The rotational kinetic energy is:

$\frac{1}{2}$ m ω^2	(2) $\frac{1}{2}I\alpha^2$	(3) $\frac{1}{2}I\omega^2$	(4) $\frac{1}{2}$ mv ²
(1) 2	(2) 2	(3) 2	(4) 2

- 2. The M.I. of a body about the given axis is 1.2 kgm₂ initially the body is at rest. In order to produce a rotational kinetic energy of 1500 joule an angular acceleration of 25 rad/sec2 must be applied about that axis for a duration of [CPMT-96,2002; RPET 1999] (2) 2 sec (1) 4 sec (3) 8 sec (4) 10 sec
- A uniform rod of length L is placed with one end in contact with the horizontal and is then inclined at an 3. angle α to the horizontal and allowed to fall without slipping at contact point. When it becomes horizontal. its angular velocity Will be [UPSEAT 2001]

$$\omega = \sqrt{\frac{3g\sin\alpha}{L}} \qquad \qquad \omega = \sqrt{\frac{2L}{3g\sin\alpha}} \qquad \qquad \omega = \sqrt{\frac{6g\sin\alpha}{L}} \qquad \qquad \omega = \sqrt{\frac{L}{g\sin\alpha}}$$
(1)

4. A cord is wound round the circumference of wheel of radius r. The fixed axis of the wheel is horizontal and moment of inertia about it is I. A weight mg is attached to the end of the cord and falls from rest. After falling through a distance h, the angular velocity of the wheel will be [MP PMT 1994; Delhi PMT 2001]

		Livii	1 141 1
2gh	$\begin{bmatrix} 2mgh \end{bmatrix}^{1/2}$	$\begin{bmatrix} 2mgh \end{bmatrix}^{1/2}$	
(1) $\sqrt{I+mr}$	(2) $\left[I + mr^2 \right]$	(3) $\lfloor I + 2mr^2 \rfloor$	(4)

- 5. A tap can be operated easily using two fingers because (1) The force available for the operation will be more
 - (2) This helps application of angular forces
 - (3) The rotational effect is caused by the couple formed
 - (4) The force by one finger overcomes friction and other finger provides the force for the operation
- 6. In the pulley system (stick to each other) shown, if radii of the bigger and smaller pulley are 2 m and 1 m respectively and the acceleration of block A is 5 m/s₂ in the downward direction, then the acceleration of block B will be:



[Manipal MEE 1995: BVP 2003]

SECTION (G) : ANGULAR MOMENTUM & ITS CONSERVATION

1.	On account of melting (1) increases	of ice at the north pole th (2) decreases	ne moment of inertia of s (3) remains unchanged	pinning earth d (4) depends on the time
2.	Which of the following (1) moment of momen (3) Moment of charge	quantity is direction less tum	(2) Moment of force (4) Moment of inertia	
3.	Two rigid bodies A and inertia of A and B abou of angular momentum (1) 25	d B rotate with rotational ut the axis of rotation are (L _A) of A to the angular n (2) 5/4	kinetic energies E _A and I _A and I _B respectively. If I nomentum (L _B) of B is (3) 5	E _B respectively. The moments of $I_A = I_B/4$ and $E_A = 100 E_B$ the ratio [JIPMER 2001,2002] (4) 1/4
4.	The moments of inertia are equal. If their kinet $\frac{K_A}{K_B} > 1$	a of two rotating bodies A ic energies be K _A and K _B (2) $\frac{K_B}{K_A} > 1$	and B are I _A and I _B (I _A > , respectively, then (3) $\frac{K_A}{K_B} = 1$	I _B) and their angular momentum (4) $\frac{K_A}{K_B} = \frac{1}{2}$
5.	When a body rotates a (1) linear velocity	about an axis the quantity (2) angular velocity	which remains same for (3) linear acceleration	r all its particles, is (4) angular momentum
6.	The time rate of chang (1) angular velocity	e of angular momentum (2) angular acceleratio	is called n (3) force	(4) torque
7.	The torque applied to a s. in 5 s, is	a ring revolving about its	own axis so as to chang	ge its angular momentum by 2 J-
8.	When a mass is rotatir (1) radius (3) a line perpendicula	ng in a plane about a fixe r to the plane of rotation	d point, its angular mom (2) the tangent to the c (4) none of the above	entum is directed along orbit
9.	A particle of mass mathematic heat heat heat heat heat heat heat heat	moves along line PC with	n velocity u as shown. W	/hat is the angular momentum of [AIEEE 2002]
			C	
	(1) muL	(2) mul	(3) mur	(4) zero

10.The angular speed of a body changes from ω_1 to ω_2 without applying a torque but due to change in its
moment of inertia. The ratio of radii of gyration in the two cases is[BHU 2002]

(1) $\sqrt{\omega_2} : \sqrt{\omega_1}$ (2) $\sqrt{\omega_1} : \sqrt{\omega_2}$ (3) $\omega_1 : \omega_2$ (4) $\omega_2 : \omega_1$

- 11.If the radius of the earth suddenly contracts to half of its present value, then the duration of day will be
of
(1) 6 hours[RPMT 1999; Kerala 2002; AMU (Med.) 1999]
(3) 18 hours(4) 24 hours
- 12. If the earth is treated as a sphere of radius R and mass M. Its angular momentum about the axis of rotation with period T is [Pb, PET 2004]

πMR^3	$MR^2\pi$	$2\pi MR^2$	$4\pi MR^2$
(1) T	(2) T	(3) 5T	(4) 5T

13.	A thin circular ring of n Two objects each of ma now rotates with an an	nass M and radius R is r ass m, are attached gent gular velocity	otating about its axis wit ly to the opposite ends o [IIT 19	th a constant angular velocity ω f a diameter of the ring. The ring 83; MP PMT 1994]). J
	<u>WM</u>	$\frac{\omega(M-2m)}{M}$		$\frac{\omega(M+2m)}{M}$	
	(1) M+m	(2) M + 2m	(3) M+2m	(4) M	
14.	What remains constant (1) Potential energy	t in the field of central fo (2) Kinetic energy	rce (3) Angular momentum	[RPET 1996] n (4) Linear momentum	
15.	If a gymnast, sitting on	a rotation stool with his a	arms outstretched, sudde	enly lowers his hands	1
	(1) The angular velocity(3) The angular velocity	y decreases y stays constnat	(2) His moment of inert (4) The angular mome	tia decreases ntum increases	I
16.	A uniform heavy disc is perpendicular to the pl vertically on the disc ar (1) ω	arotating at constant anguane of the disc. Let L be nd sticks to it. Which will (2) ω and L both	ular velocity ω about a ve e its angular momentum. be constant (3) L only	ertical axis through its eentre and A lump of plasticine is dropped [AMU (Me d.) 2001] (4) Neither ω nor L	t t
17.	A disc is rotating with a	in angular speed of ω . If	a child sits on it, which o	f the following is conserved	
	(1) Kinetic energy	(2) Potential energy	(3) Linear momentum	(4) Angular momentum	
18.	A homogeneous disc of angular velocity of 4 ra (1) 1.2kg-m/s	of mass 2 kg and radius dian/s. The linear momen (2) 1.0 kg-m/s	15 cm is rotating about ntum of the disc is (3) 0.6 kg-m/s	its axis (which is fixed) with an [CPMT 1989] (4) None of the above	ſ
19.	A mass M is moving w respect to origin or z-a: (1) Zero	rith a constant velocity al xis is [IIT 1985, 97 (Canc (2) Remains constant	long a line parallel to x-a celled); MP PET 1996; M (3) Goes on increasing	axis. Its angular momentum with /IP PMT 1997; Raj. PET 2000] J (4) Goes on decreasing	า
20.	The moment of momer (1) Couple	ntum is called (2) Torque	(3) Impulse	[RPET-2000] (4) Angular momentum	
21.	A flywheel rotating abo sec. The moment of ine (1) 0.6 kg x m ₂	ut a fixed axis has a kine ertia of the wheel about t (2) 0.15 kg x m₂	etic energy of 360 joule w he axis of rotation is (3) 0.8 kg x m ₂	vhen its angular speed is 30 rad [CBSE 1990] (4) 0.75 kg x m₂	/
22.	A particle of mass m is centripetal force acting (1) L ₂ /mr	s rotating in a plane in c on the particle is (2) L ₂ m/r ₂	ircular path of radius r. I (3) L2/m2r2	ts angular momentum is L. The [MP PMT 2001] (4) L₂/mr₃	Э
23.	The position of a part momentum is perpendi (1) X-axis	icle is given by $\vec{r} = (\hat{i} + icular to)$	$2\hat{j} - \hat{k}$ and momentum (2) Y-axis	$P = (3\hat{i} + 4\hat{j} - 2\hat{k})$. The angula [CPMT 2000]	r
24.	(3) Z-axis A mass m is moving momentum about the c	with constant velocity al origin :	(4) Line at equal angle long a line parallel to x	s to all the three axes -axis beyond origin. Its angula [RPMT-2004]	r
	(1) remains constant	(2) is zero	→ v (3) increases	(4) decreases	
25.	A solid sphere is rotati	ng about a diameter at a	n angular velocity ω . If it	t cools so that its radius reduces	s
	$\frac{1}{n}$ to $\frac{1}{n}$ of its original value	ie, its angular velocity be	comes	[RPMT-2007]	

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	$\frac{\omega}{z}$	$\frac{\omega}{r^2}$		
	(1) n	(2) n ⁻	(3) nω	(4) n ₂ ω
26.	A particle performing un and its kinetic energy is L	iform circular motion has halved, then the new ar	angular momentum L. If ngular momentum is :	its angular frequency is doubled [RPMT-2008] L
	(1) 4	(2) 2L	(3) 4L	(4) 2
27.	A body is rotating with kinetic energy of rotation	angular momentum L. If n is	I is its moment of inert	ia about the axis of rotation, its [RPMT-2011]
	<u>1</u>	<u>1</u>	<u>1</u>	$\underline{1} \underline{L^2}$
	(1) 2 IL ₂	(2) 2 IL	(3) 2 (I ₂ L)	(4) 2 I
28.	A constant torque acting	gon a uniform circular w	heel changes its angular	momentum from A_0 to $4A_0$ in 4
	sec. the magnitude of th (1) 4A ₀	nis torque is : (2) A₀	(3) 3A ₀ /4	(4) 12A ₀
29.	A particle moves with a	constant velocity paralle	l to the X-axis. Its angula	r momentum with respect to the
	origin. (1) is zero (3) goes on increasing		(2) remains constant (4) goes on decreasing	
30	A particle performs unif	form circular motion with	an angular momentum	I If the frequency of particle's
50.	motion is doubled and it (1) 2L	(2) 4L	d, the angular momentum (3) L/2	n becomes : (4) L/4
31.	A person sitting firmly	over a rotating stool ha	as his out stretched. If	he folds his arms, his angular
	momentum about the ax (1) increases	xis of rotation (2) decreases	(3) remains unchanged	(4) doubles
32.	A conical pendulum con O the centre of the circl	sists of a simple pendulutile in which the pendulur	um moving in a horizonta n bob moves and ω the	l circle as shown. C is the pivot, constant angular velocity of the
	bob. If L is the angular	momentum about point	C, then	
		//		
		/		
		۱¢	•0	
	,	ω		
	(1) L is constant		(2) only direction of L is	s constant
	(3) only magnitude of L	is constant	(4) none of the above.	
33.	In the above problem if	L is the angular momen	itum about the axis CO. I	hen.
	(1) \bot is constant	ie ine englien nerver	(2) only direction of L is	s constant
	(3) only magnitude of L	is constant	(4) none of the above.	
34.	The motion of planets in	the solar system is an e	example of the conservat	
	(1) Mass (3) Angular momentum		(2) Linear momentum (4) Energy	[,
35.	A particle is in uniform o	circular motion in a horize	ontal plane. Its angular n	nomentum is constant when the
	(1) centre of the circle(3) any point inside the circle	circle	(2) any point on the circ(4) any point outside the	cumference of the circle

- **36.** A particle of mass m is projected with a velocity v making an angle 45° with the horizontal. The magnitude of the angular momentum of the projectile about the point of projection when the particle is at its maximum height h, is :-
 - (1) zero (2) $\frac{mv^3}{4\sqrt{2g}}$ (3) $\frac{mv^3}{\sqrt{2g}}$ (4) $m^2\sqrt{2gh^3}$
- **37.** A circular wooden loop of mass m and radius R rests flat on a horizontal frictionless surface. A bullet, also of mass m, and moving with a velocity V, strikes the loop and gets embedded in it. The thickness of the loop is much smaller than R. The angular velocity with which the system rotates just after the bullet strikes the loop is



SECTION (H): COMBINED TRANSLATIONAL + ROTATION MOTION (KINEMATICS)

1. A solid spherical ball rolls on an inclined plane without slipping. The ratio of rotational energy and total energy is [CBSE 1993; BHU 1997; MP PET 2002; UPSEAT 2002]

<u> </u>	2	<u> </u>	3
(1) 5	(2) 7	(3) 5	(4) 7

2. When a sphere of moment of inertia I about its centre of gravity and mass 'm' rolls from rest down an inclined plane without slipping. its kinetic energy is [Delhi PMT 1993; Raj. PET 2001]

$\frac{1}{1}$ $I\omega^2$	$\frac{1}{-}$ mv ²		$\frac{1}{-I\omega^2}$ +	$\frac{1}{mv^2}$
(1) 2	(2) 2	(3) Iω + mv	(4) 2	2

3. A ring of mass 1 kg and diameter 1m is rolling on a plane road with a speed 2m/s. Its kinetic energy would be

	(1) 1 joule	(2) 4 joule	(3) 2 joule	(4) 0.5 joule
--	-------------	-------------	-------------	---------------

- A solid cylinder starts rolling from a height h on an inclined plane. At some instant t, the ratio of its rotational K.E. and the total K.E. would be
 (1) 1:2
 (2) 1:3
 (3) 2:3
 (4) 1:1
- 5. A solid homogeneous sphere is moving on a rough horizontal surface partly rolling and partly sliding. During this kind of motion of the sphere [CBSE PMT 1992]
 - (1) Total kinetic energy is conserved
 - (2) The angular momentum of the sphere about the point of contact with the plane is conserved
 - (3) Only the rotational kinetic energy about the centre of mass is conserved
 - (4) Angular momentum about the centre of mass is conserved
- A solid cylinder 30 cm in diameter at the top of an inclined plane 2.0 m high is released and rolls down the incline without loss of energy due to friction. Its linear speed at the bottom is [PMT 1999] (1) 5.29 m/sec
 (2) 4.1 x 10₃ m/sec
 (3) 51 m/sec
 (4) 51 cm/sec
- 7. The total energy of disc of mass M and velocity u rolling an inclined plane without slipping is :

			[RPMT_2004]
3	2	3	1
(1) 4 Mu ₂	(2) 5 Mu ₂	(3) 2 Mu ₂	(4) 1 ³ Mu ₂

8. If a sphere rolling on an inclined plane with velocity u without slipping, the vertical height of the incline in terms of velocity will be : [RPMT_2004]



- 9.A sphere of diameter 0.2 m and mass 2 kg is rolling on an inclined plane with velocity v = 0.5 m/s. The
kinetic energy of the sphere is :
(1) 0.1 J[RPMT-2006]
(3) 0.5 J(1) 0.1 J(2) 0.3 J(3) 0.5 J(4) 0.42 J
- 10. A solid sphere rolls down on two different inclined planes of same height, but of different inclinations. In both cases [RPMT-2007]
 - (1) speed and time of descent will be same
 - (2) speed will be same but time of descent will be different
 - (3) speed will be different, but time of descent will be same
 - (4) speed and time of descent both are different
- **11.** A smooth sphere A is moving on a frictionless horizontal plane with angular speed ω and centre of mass velocity v. It collides elastically and head on with an identical sphere B at rest. Neglect friction everywhere. After the collision, their angular speeds are $\omega_A \& \omega_B$ respectively. Then:

(1)
$$\omega_{A} < \omega_{B}$$
 (2) $\omega_{A} = \omega_{B}$ (3) $\omega_{A} = \omega$ (4) $\omega_{B} = \omega$

12. A wheel of bicycle is rolling without slipping on a level road. The velocity of the centre of mass is v_{cm}; then true statement is : [AIPMT-2001]



(1) The velocity of point A is $2v_{cm}$ and velocity of point B is zero

- (2) the velocity of point A is zero and velocity of point B is 2vcm
- (3) the vleocity of point A is $2v_{\mbox{\tiny cm}}$ and velocity of point B is $v_{\mbox{\tiny cm}}$
- (4) the velocities of both A and B are v_{cm}

13. P is the point of contact of a wheel and the ground. The radius of wheel is 1m. The wheel rolls on the ground without slipping. The displacement of point P when wheel completes half rotation is :-[AIPMT-2002]

	(1) 2 m	(2) $\sqrt{\pi^2 + 4}$ m	(3) πm	(4) $\sqrt{\pi^2 + 2}$ m
14.	A disc is rolling on an	inclined plane. What frac	tion of its total energy wi	Il be as rotational energy :
	(1) 4/3	(2) 1/3	(3) 1/2	[RPW1_2002] (4) 2/3
15.	If rotational kinetic en (1) Ring	ergy is 50% of translation (2) Cylinder	al kinetic energy, then th (3) Hollow sphere	ne body is [RPMT 2003] (4) Solid sphere
16.	A solid sphere is rollir and translational kiner	ng without slipping on a h tic energy is 2	orizontal surface. The ra	tio of its rotational kinetic energy [RPMT-2003] 7
	(1) $\frac{2}{9}$	(2) $\frac{2}{5}$	(3) $\frac{2}{7}$	(4) $\frac{7}{2}$

- **17.** A solid sphere, a hollow sphere and a ring are released from top of an inclined plane (frictionless) so that they slide down the plane. The maximum acceleration down the plane is for (no rolling) :
 - (1) solid sphere (2) hollow sphere (3) ring (4) all same

[AIEEE 4/300 2002]

(4) All will be same

18. A disc is moving without slipping on ground then the relation between magnitude of velocity of points P, C and Q is [distance CP = CQ]

 [JEE Sc. 2004' 3/84]

(1)
$$Q > C > P$$
 (2) $P > C > Q$ (3) $C > Q > P$

19. A sphere is rolling without slipping on a fixed horizontal plane surface. In the figure, A is the point of contact, B is the centre of the sphere and C is its topmost point. Then, [JEE 2009, 4/160, -1]



- **20.** The centre of a wheel rolling with out slipping in a plane surface moves with speed u_0 . A particle on the rim of the wheel at the same level as the centre will be moving at speed (1) zero (2) u_0 (3) $\sqrt{2}u_0$ (4) $2u_0$
- **21.** A hollow smooth uniform sphere A of mass 'm' rolls without sliding on a smooth horizontal surface. It collides elastically and headon with another stationary smooth solid sphere B of the same mass m and same radius. The ratio of kinetic energy of 'B' to that of 'A' just after the collision is :



- 22. A solid sphere, a hollow sphere and a disc, all having same mass and radius, are placed at the top of an incline and released. The friction coefficients between the objects and the incline are same and not sufficient to allow pure rolling. The smallest kinetic energy at the bottom of the incline will be achieved by
 - (1) the solid sphere(2) the hollow sphere(3) the disc(4) all will achieve same kinetic energy.
- **23.** A hollow sphere and a solid sphere having same mass and same radii are rolled down (without sliding) a rough inclined plane.
 - (1) The hollow sphere reaches the bottom first
 - (2) The solid sphere reaches the bottom with greater speed.
 - (3) The solid sphere reaches the bottom with greater kinetic energy
 - (4) The two spheres will reach the bottom with same linear momentum
- A solid sphere, a hollow sphere and a disc, all having same mass and radius, are placed at the top of an incline and released. The friction coefficients between the objects and the incline are same and not sufficient to allow pure rolling. Least time will be taken in reaching the bottom by(1) the solid sphere (2) the hollow sphere (3) the disc (4) all will take same time.

25. A plank P is placed on a solid cylinder S, which rolls on a horizontal surface. The two are of equal mass. There is no slipping at any of the surfaces in contact. The ratio of the kinetic energy of P to the kinetic energy of S is:



26. A large spool of rope lies on the ground as shown in the fig. The end, labelled X is pulled a distance S in the horizontal direction. The spool rolls without slipping. The centre of mass of the spool moves a distance



27. A thin string is wrapped several times around a cylinder kept on a rough horizontal surface. A boy standing at a distance ℓ from the cylinder draws the string towards him as shown in figure. The cylinder rolls without slipping. The length of the string passed through the hand of the boy while the cylinder reaches his hand is



SECTION (I): COMBINED TRANSLATIONAL & ROTATIONAL MOTION (DYNAMICS)

- 1.The velocity of centre of mass of a disc rolling on an inclined plane changes from V to 2V at any instant
of time. If M is the mass of disc then increases in its kinetic energy will be
(1) (9/4) MV_2 (2) $MV_2/2$ (3) MV_2 (4) $3MV_2$
- A solid sphere and a solid cylinder having the same mass and radius, roll down the same incline. The ratio of their acceleration will be

 (1) 15:14
 (2) 14:15
 (3) 5:3
 (4) 3:5
- **3.** A solid sphere and a hollow sphere are thrown horizontally from a cliff with equal velocities, respectively. Then which sphere reaches first on earth ? [AIPMT-2000]
 - (1) Solid sphere
 - (2) Hollow sphere
 - (3) Both sphere simultaneously
 - (4) We cannot say because masses of spheres are not given
- 4. A sphere S rolls without slipping, moving with a constant speed on a plank P. The friction between the upper surface of P and the sphere is sufficient to prevent slipping, while the lower surface of P is smooth and rests on the ground. Initially, P is fixed to the ground by a pin N. If N is suddenly removed:



- (1) S will begin to slip on P
- (2) P will begin to move backwards
- (3) the speed of S will decrease and its angular velocity will increase
- (4) there will be no change in the motion of S and P will still be at rest.
- 5. A body is given translational velocity and kept on a surface that has sufficient friction. Then:
 - (1) body will move forward before pure rolling (2) body will move backward before pure rolling
 - (3) body will start pure rolling immediately
- (4) none of these
- 6. A body of mass m and radius r is rotated with angular velocity ω as shown in the figure & kept on a surface that has sufficient friction then the body will move :
 - (1) backward first and then move forward(3) will always move forward

(2) forward first and then move backward (4) none of these

7. As shown in the figure, a disc of mass m is rolling without slipping with an angular velocity ω . The portion AB is rough and BC is smooth. When it crosses point B disc will be in :



(1) translational motion only(3) rotational motion only

- (2) pure rolling motion (4) none of these
- (4) Hone of these
- 8. A cylinder rolls up an inclined plane, reaches some height and then rolls down (without slipping throughout these motions). The directions of the frictional force acting on the cylinder are :

[JEE - 02 (Scr.) 3/90]

- (1) Up the incline while ascending and down the incline while descending
- (2) Up the incline while ascending as well as descending
- (3) Down the incline while ascending and up the incline while descending
- (4) Down the incline while ascending as well as descending.
- **9.** A solid uniform disc of mass m rolls without slipping down an inclined plane with an acceleration a. The frictional force on the disc due to surface of the plane is



10. A disc is performing pure rolling on a smooth stationary surface with constant angular velocity as shown in figure. At any instant, for the lower most point of the disc



(1) Velocity is v, acceleration is zero (2) Velocity is zero, acceleration is zero

 v^2

(3) velocity is v, acceleration is R.

- (4) velocity is zero, acceleration is $\frac{v^2}{R}$
- **11.** A drum of radius R and mass M, rolls down without slipping along an inclined plane of angle θ. The frictional force : [AIPMT-2005]
 - (1) converts translational energy to rotational energy
 - (2) dissipates energy as heat
 - (3) decreases the rotational motion
 - (4) decrease the rotational and translational motion
 - **12.** An annular ring with inner and outer radii R_1 and R_2 is rolling without slipping with a uniform angular speed. The ratio of the forces experienced by the two particles situated on the inner and outer parts of F_1

the ring,
$$\overline{F_2}$$
 is : [AIEEE 4/300 2005]
(1) $\frac{R_2}{R_1}$ (2) $\left(\frac{R_1}{R_2}\right)^2$ (3) 1 (4) $\frac{R_1}{R_2}$

13. A round uniform body of radius R, mass M and moment of inertia I rolls down (without slipping) an inclined plane making an angle θ ? with the horizontal. Then its acceleration is :[AIEEE-2007; 3/120] gsin θ gsin θ gsin θ gsin θ gsin θ

$$\frac{g\sin\theta}{1+I/MR^2} \qquad (2) \frac{g\sin\theta}{1+MR^2/I} \qquad (3) \frac{g\sin\theta}{1-I/MR^2} \qquad (4) \frac{g\sin\theta}{1-MR^2/I}$$

14. A smooth inclined plane fixed in a car accelerating on a horizontal road is shown in figure. The angle of incline θ is related to the acceleration a of the car as $a = g \tan \theta$. If the sphere is set in pure rolling on the incline



- (1) it will continue pure rolling
- (3) its angular velocity will increase

(2) it will slip up the plane

(4) its angular velocity will decrease.

SECTION (J) : CONSERVATION OF ANGULAR MOMENTUM (COMBINED TRANSLATION & ROTATIONAL MOTION)

- **1.** A uniform sphere is released on a smooth inclined plane from the top. When it moves down its angular momentum is:
 - (1) conserved about every point
 - (2) conserved about the point of contact only
 - (3) conserved about the centre of the sphere only
 - (4) conserved about any point on a fixed line parallel to the inclined plane and passing through the centre of the ball.
- A uniform thin ring of mass 0.4 kg rolls without slipping on a horizontal surface with a linear velocity of 10 cm/s. The kinetic energy of the ring is :

 (1) 4 x 10-3 joules
 (2) 4 x 10-2 joules
 (3) 2 x 10-3 joules
 (4) 2 x 10-2 joules
- A wheel and an axle is made to rotate about a horizontal axis with the help of a body of mass 5 kg attached to a string wound around the axle. The radius of the axle is 10 cm. The body falls vertically throught 5 m is 10 s starting from rest. The moment of inertial of the wheel and axle is [RPMT-2014] (1) 3.85 kg m₂ (2) 4.85 kg m₂ (3) 5.85 kg m₂ (4) 2.85 kg m₂
- 4. A disc of mass M and radius R is rolling with angular speed ω on a horizontal plane as shown. The magnitude of angular momentum of the disc about the origin O is [JEE 99' 2/200]



5. A sphere is released on a smooth inclined plane from the top. When it moves down its angular momentum is:

- (1) conserved about every point
- (2) conserved about the point of contact only
- (3) conserved about the centre of the sphere only
- (4) conserved about any point on a fixed line parallel to the inclined plane and passing through the centre of the ball.

SECTION (K): TOPPLING

1. A uniform cube of side a and mass m rests on a rough horizontal table. A horizontal force 'F' is applied 3a

normal to one of the faces at a point that is directly above the centre of the face, at a height 4 above the base. The minimum value of 'F' for which the cube begins to tilt about the edge is(assume that the cube does not slide). [JEE - 84]

2. A cubical block of side L rests on a rough horizontal surface with coefficient of friction μ. A horizontal force F is applied on the block as shown. If the coefficient of friction is sufficiently high so that the block does not slide before toppling, the minimum force required to topple the block is [JEE - 2000 (Scr' 1/35]

(1) Infinitesimal (2)
$$\frac{mg}{4}$$
 (3) mg/2 (4) mg (1 - μ)
Exercise-2

1. The moment of inertia of a uniform semicircular wire of mass M and radius r about a line perpendicular to the plane of the wire and passing through the centre of mass of the system

(1)
$$Mr_2 \left(1 - \frac{4}{\pi^2}\right)$$
 (2) $Mr_2 \left(1 + \frac{4}{\pi^2}\right)$ (3) $Mr_2 \left(1 - \frac{\pi^2}{4}\right)$ (4) $Mr_2 \left(1 + \frac{\pi^2}{4}\right)$

2. Find moment of inertia of a semi circular disc about axis passing through center of mass and perpendicular to its plane.

(1)
$$MR_2 \left(\frac{1}{2} - \frac{16}{9\pi^2}\right)$$
 (2) $MR_2 \left(\frac{1}{2} + \frac{16}{9\pi^2}\right)$ (3) $MR_2 \left(\frac{1}{2} - \frac{9\pi^2}{16}\right)$ (4) $MR_2 \left(\frac{1}{2} + \frac{9\pi^2}{16}\right)$

A thin wire of length L and linear mass density ρ is bent into a circular loop with centre at O as shown.
 The moment of inertia of the loop about the axis XX' is [JEE - 2000 Scr' 1/35]



4. The beam and pans of a balance have negligible mass. An object weighs W₁ when placed in one pan and W₂ when placed in the other pan. The weight W of the object is :

(1)
$$\sqrt{W_1W_2}$$
 (2) $\sqrt{(W_1 + W_2)}$ (3) $W_{12} + W_{22}$ (4) $(W_{1-1} + W_{2-1})/2$

- 5. A weightless ladder 20 ft. long rests against a frictionless wall at an angle of 60° from the horizontal. A 150 pound man is 4 ft from the bottom of the ladder. A horizontal force is needed to keep it from slipping. Choose the correct magnitude of force from the following : [AIPMT-1998] (2) 100 pound (1) 17.3 pound (3) 120 pound (4) 150 pound
- 6. An equilateral triangle ABC formed from a uniform wire has two small identical beads initially located at A. The triangle is set rotating about the vertical axis AO. Then the beads are released from rest simultaneously and allowed to slide down, one along AB and the other along AC as shown. Neglecting frictional effects, the quantities that are conserved as the beads slide down, are [JEE - 2000 Scr.' 1/35]



- (1) Angular velocity and total energy (kinetic energy and potential energy)
- (2) Total angular momentum and total energy
- (3) Angular velocity and moment of inertia about the axis of rotation
- (4) Total angular momentum and moment of inertia about axis AO
- If $\tau \times L = 0$ for a rigid body, where τ = resultant torque & L = angular momentum about a point and 7. both are non-zero. Then :

(3) L will increase (4) L may increase (2) LI = constant (1) L = constantA uniform ring of radius R is given a back spin of angular velocity V₀/2R and thrown on a horizontal rough 8. surface with velocity of center to be V_0 . The velocity of the centre of the ring when it starts pure rolling will be $(1) V_0/2$ $(2) V_0/4$ $(3) 3V_0/4$ (4) 0

9. A cubical block of side a is moving with velocity v on a horizontal smooth plane, as shown It hits a ridge at point O. The angular speed of the block after it hits O is . [JEE - 99' 2/200]

<u>3v</u>	<u>3v</u>	$\sqrt{3}v$	
(1) ^{4a}	(2) ^{2a}	(3) √2a	(4) zero

√4gh

(2)

10. A solid sphere of radius R is placed on a smooth horizontal surface. A horizontal force F is applied at height h from the lowest point. For the maximum acceleration of the centre of mass : [AIPMT_2002] (1) h = R(2) h = 2R(4) the acceleration will be same whatever h may be (3) h = 0

A solid cylinder of mass M and radius R rolls without slipping down an inclined plane of length L and 11. height h. What is the speed of its centre of mass when the cylinder reaches its bottom ? [AIPMT-2003] gh (3) $\sqrt{2gh}$

gh 3 (1)

A circular disc X of radius R is made from an iron plate of thickness t, and another disc Y of radius 4R is 12. made from an iron plate thickness t/4. Then the relation between the moment of inertia Ix and Iy is : [AIEEE 4/300 2003]

- (1) $I_Y = 32I_X$ (2) $I_Y = 16I_X$ (3) $I_Y = I_X$ (4) $I_Y = 64 I_X$
- One quarter sector is cut from a uniform circular disc of radius R. This sector has mass M. It is made to rotate about a line perpendicular to its plane and passing through the centre of the original disc. Its moment of inertial about the axis of rotation is : [JEE 01 (Scr.)' 3/105]



14. A disc has mass 9m. A hole of radius $\overline{3}$ is cut from it as shown in the figure. The moment of inertia of the remaining part about an axis passing through the centre 'O' of the disc and perpendicular to the plane of the disc is : [JEE Scr. 2005, 3/84]



15. A solid sphere of radius R has moment of inertia I about its geometrical axis. If it is melted into a disc of radius r and thickness t. If it's moment of inertia about the tangential axis (which is perpendicular to plane of the disc), is also equal to I, then the value of r is equal to : [JEE 2006, 3/184]



- 16. STATEMENT 1 : If there is no external torque on a body about its centre of mass, then the velocity of the center of mass remains constant. [JEE-2007, 3/162] because
 - **STATEMENT 2**: The linear momentum of an isolated system remains constant.
 - (1) Statement-1 is True, Statement-2 is True; Statement-2 is a correct explanation for Statement-1
 - (2) Statement-1 is True, Statement-2 is True; Statement-2 is NOT a correct explanation for Statement-1
 - (3) Statement-1 is True, Statement-2 is False
 - (4) Statement-1 is False, Statement-2 is True.
- 17. STATEMENT -1 : Two cylinders, one hollow (metal) and the other solid (wood) with the same mass and identical dimensions are simultaneously allowed to roll without slipping down an inclined plane from the same height. The hollow cylinder will reach the bottom of the inclined plane first. [JEE-2008, 3/163] and

STATEMENT -2 : By the principle of conservation of energy, the total kinetic energies of both the cylinders are identical when they reach the bottom of the incline. [JEE-2008, 3/163]

- (1) STATEMENT -1 is True, STATEMENT -2 is True; STATEMENT -2 is a correct explanation for STATEMENT -1
- (2) STATEMENT -1 is True, STATEMENT-2 is True; STATEMENT -2 is NOT a correct explanation for STATEMENT -1
- (3) STATEMENT -1 is True, STATEMENT -2 is False
- (4) STATEMENT -1 is False, STATEMENT -2 is True.
- **18.** If the resultant of all the external forces acting on a system of particles is zero, then from an inertial frame, one can surely say that [JEE 2009, 4/160, -1]
 - (1) linear momentum of the system does not change in time
 - (2) kinetic energy of the system does not changes in time
 - (3) angular momentum of the system does not change in time
 - (4) potential energy of the system does not change in time
- **19.** A ring of mass M and radius R is rotating with angular speed ω about a fixed vertical axis passing through M

its centre O with two point masses each of mass 8 at rest at O. These masses can move radially outwards along two massless rods fixed on the ring as shown in the figure. At some instant the angular 8

speed of the system is $\frac{5}{9}^{\circ}$ and one of the masses is at distance of $\frac{5}{5}^{\circ}$ from O. At this instant the distance of the other mass from O is : [JEE(Advanced) 2015; 4/88, -2]



20. ABC is a triangular plate of uniform thickness. The sides are in the ratio shown in the figure. IAB, IBC, ICA are the moments of inertia of the plate about AB, BC, CA respectively. Which one of the following relations is correct [CBSE PMT 1995]





21. A uniform rectangular plate of mass m which is free to rotate about the smooth vertical hinge passing through the centre and perpendicular to the plate, is lying on a smooth horizontal surface. A particle of mass m moving with speed 'u' collides with the plate and sticks to it as shown in figure. The angular velocity of the plate after collision will be :



(1) ICA is maximum

22. A particle of mass m is moving horizontally at speed v perpendicular to a uniform rod of length d and mass M = 6m. The rod is hinged at centre O and can freely rotate in horizontal plane about a fixed vertical axis passing through its centre O. The hinge is frictionless. The particle strikes and sticks to the end of the rod. The angular speed of the system just after the collision :



23. If 'r' is the radius vector and 'P' momentum, the angular momentum L is given by L = Pr. Which of the graphs shows correctly the variation of (log L) with (log P) ? [RPMT-2014]



24. A particle is projected at time t = 0 from a point P on the ground with a speed V₀, at an angle of 45° to the horizontal. What is the magnitude of the angular momentum of the particle about P at time t= v₀/g.
[JEE-1984 6 marks]

mv_0^2	mv_0^3	mv_0^2	mv_0^3
(1) $2\sqrt{2}$ g	(2) $\sqrt{2}$ g	(3) $\sqrt{2}$ g	(4) $2\sqrt{2}$ g

25. A ball rolls without slipping. The radius of gyration of the ball about an axis passing through its centre of mass is K. If radius of the ball be R, then the fraction of total energy associated with its rotational energy will be :- [AIPMT-2003]

(1)
$$\frac{K^2}{K^2 + R^2}$$
 (2) $\frac{R^2}{K^2 + R^2}$ (3) $\frac{K^2 + R^2}{R^2}$ (4) $\frac{K^2}{R^2}$

26. A circular disk of moment of inertia I_t is rotating in a horizontal plane, about its symmetry axis, with a constant angular speed ω_r . Another disk of moment of inertia I_b is dropped coaxially onto the rotating disk. Initially the second disk has zero angular speed. Eventually both the disks rotate with a constant angular speed ω_r . The energy lost by the initially rotating disc to friction is **[AIPMT (Screening)_2010]**

$$(1) \frac{1}{2} \frac{I_b^2}{(I_t + I_b)} \omega_i^2 \qquad (2) \frac{1}{2} \frac{I_t^2}{(I_t + I_b)} \omega_i^2 \qquad (3) \frac{I_b - I_t}{(I_t + I_b)} \omega_i^2 \qquad (4) \frac{1}{2} \frac{I_b I_t}{(I_t + I_b)} \omega_i^2$$

27. A uniform rod of length ℓ is placed symmetrically on two walls as shown in figure. The rod is in equilibrium. If N₁ and N₂ are the normal forces exerted by the walls on the rod then



(3) $N_1 = N_2$ (1) $N_1 > N_2$ (2) $N_1 > N_2$ (4) N1 and N2 would be in the vertical directions.

(2) MR₂

Exercise-3

PART - I : NEET / AIPMT QUESTION (PREVIOUS YEARS)

1. If is force acting on a particle having position vector and be the torgue of this force about the origin, then [AIPMT 2009]

(1) $r.\tau \neq 0$ and $F.\tau = 0$	(2) $r.\tau > 0$ and $F.\tau < 0$
(3) $r.\tau = 0$ and $F.\tau = 0$	(4) $r.\tau = 0$ and $F.\tau \neq 0$

2. Four identical thin rods each of mass M and length ℓ , form a square frame. Moment of intertia of this frame about an axis through the centre of the square and perpendicular to its plane is [AIPMT 2009] 40

(1)
$$\frac{4}{3}$$
 M ℓ_2 (2) $\frac{2}{3}$ M ℓ_2 (3) $\frac{13}{3}$ M ℓ_2 (4) $\frac{1}{3}$ M ℓ_2

3. From a circular disc of radius R and mass 9M, a small disc of mass M and radius ³ is removed concentrically. The moment of inertia of the remaining disc about an axis perpendicular to the plane of [AIPMT (Mains)_2010] the disc and passing through its centre is

(1)
$$\frac{40}{9}$$
 MR²

(3) 4MR₂

-MR²

9

(4)

- 4. The instantaneous angular position of a point on a rotating wheel is given by the equation $\theta(t) = 2t_3 - 6t_2$. The torque on the wheel becomes zero at : [AIPMT (Screening) 2011] (3) t = 0.25 s (1) t = 1s(2) t = 0.5 s(4) t = 2s
- The moment of inertia of a thin uniform rod of mass M and length L about an axis passing through its 5. midpoint and perpendicular to its length is lo. Its moment of inertia about an axis passing through one of its ends and perpendicular to its length is : [AIPMT (Screening) 2011] (1) $I_0 + ML_2/2$ (2) $I_0 + ML_2/4$ (3) $I_0 + 2ML_2$ (4) $I_0 + ML_2$

6. When a mass is rotating in a plane about a fixed point, its angular momentum is directed along : (1) a line perpendicular to the plane of rotation [RBD AIPMT Pre 2012] (2) the line making an angle of 45° to the plane of rotation.

- (3) the radius
- (4) the tangent to the orbit.
- 7. A solid cylinder of mass 3 kg is rolling on a horizontal surface with velocity 4ms-1. It collides with a horizontal spring of force constant 200 Nm-1. The maximum compression produced in the spring will be: [AIPMT-Pre-2012]

ABC is an equilateral triangle with O as its centre. $\vec{F_1}$, $\vec{F_2}$ and $\vec{F_3}$ represent three forces acting along 8. the sides AB, BC and AC respectively. If the total torque about O is zero the magnitude of F_3 is : [AIPMT Pre 2012]



9. A circular platform is mounted on a frictionless vertical axle. Its radius R = 2m and its moment of inertia about the axle is 200 kgm₂. it is initially at rest. A 50 kg man stands on the edge of the platform and begins to walk along the edge at the speed of 1ms₋₁ relative to the ground. Time taken by the man to complete one revolution is : [AIPMT 2012 (Mains)]

(1)
$$\pi s$$
 (2) $\frac{3\pi}{2}s$ (3) $2\pi s$ (4) $\frac{\pi}{2}s$

10. The moment of inertia of a uniform circular disc is maximum about an axis perpendicular to the disc and passing through : [AIPMT 2012 (Mains)]



11. A small object of uniform density rolls up a curved surface with an initial velocity 'v'. It reaches upto a $3v^2$

maximum height of	4g	with respect to the	e initia	al position.	The object is		[NEET_2013]
(1) Solid sphere		(2) Hollow sphere		(3) Disc		(4) Ring	

(1) g/L

12. A rod PQ of mass M and length L is hinged at end P. The rod is kept horizontal by a massless string tied to point Q as shown in figure. When string is cut, the initial angular acceleration of the rod is :



- **13.**A solid cylinder of mass 50 kg and radius 0.5 m is free to rotate about horizontal axis. A massless string
is wound round the cylinder with one end attached to it and other hanging freely. Tension in the string
required to produce an angular acceleration of 2 revolutions s_{-2} [AIPMT-2014]
(4) 157 N(1) 25 N(2) 50 N(3) 78.5 N(4) 157 N
- **14.** A rod of weight W is supported by two parallel knife edges A and B and is in equilibrium in a horizontal position. The knives are at a distance d from each other. The centre of mass of the rod is at distance x from A. The normal reaction on A is : [AIPMT-2015]

Wd	$\overline{vv(a-x)}$	W(d-x)	VVx
(1) ×	(2) ^χ	(3) d	(4) d

15. Three identical spherical shells, cach of mass m and radius r are placed as shown in figure. Consider an axis XX' which is touching to two shells and passing through diameter of third shell. Moment of inertia of the system consisting of these three sphereical shell about XX' axis is : [AIPMT-2015]



16. Point masses m_1 and m_2 are placed at the opposite ends of a rigid of length L, and negligible mass. The rod is to be set rotating about an axis perpendicular to it. The position of point P on this rod through which the axis should pass so that the work required to set the rod rotating with angular velocity ω_0 is minimum, is given by :



17. A force $\vec{F} = \alpha \hat{i} + 3\hat{j} + 6\hat{k}$ is acting at a point $\vec{r} = 2\hat{i} - 6\hat{j} - 12\hat{k}$. The value of α for which angular momentum about origin is conserved is :

•				
•	(1) 2	(2) zero	(3) 1	(4) -1
18.	From a disc of radiu is cut. What is the n through the centre? (1) 9MR ² /32	us R and mass M, a circ noment of inertia of the r (2) 15MR ² /32	ular hole of diameter R remaining part of the dis (3) 13MR ² /32	, whose rim passes through the centre sc about at perpendicular axis, passing [AIPMT-2016] (4) 11 MR ² /32
19.	A disk and a sphe altitude and length. (1) Depends on the (3) Sphere	re of same radius but o Which one of the two o ir masses	different masses roll of bjects gets to the botto (2) Disk (4) both reach at	ff on two inclined planes of the same m of the plane first ? [AIPMT-2016] the same time
20.	A uniform circular of plane and passes acceleration of 2.0	lisc of radius 50 cm at i through its centre. it is rad s ⁻² . Its net accelerat	rest is free to turn about s subjected to a torque tion in ms ⁻² at the end o	ut an axis which is perpendicular to its e which produces a constant angular of 2.0 s is approximately: [AIPMT-2016]
	(1) 3.0	(2) 8.0	(3) 7.0	(4) 6.0
21.	Two rotating bodies kinetic energy of ro	A and B of masses m tation. If L_A and L_B be th	and 2m with moments o eir angular momenta re	of inertia I _A and I _B (I _B > I _A) have equal espectively, then [NEET 2016]
	(1) L _A > L _B	(2) $L_{A} = \frac{L_{B}}{2}$	(3) L _A = 2L _B	$(4) L_B > L_A$
22.	A solid sphere of m and same radius is The ratio of their kir (1) 3 : 1	ass m and radius R is r also rotating about its ge netic energies of rotatior (2) 2:3	otating about its diame eometrical axis with an n (E _{sphere} / E cylinder) w (3) 1 : 5	angular speed twice that of the sphere. (4) 1:4
23.	A light rod of length system about an ax	I has two masses m_1 a is perpendicular to the	nd m_2 attached to its tw rod and passing throug	vo ends. The moment of inertia of the http://www.commonstance.com/ h the centre of mass is :[NEET 2016]
	(1) $\sqrt{m_1 m_2} []^2$	(2) $\frac{m_1m_2}{m_1+m_2}$	(3) $\frac{m_1m_2}{m_1+m_2}$	(4) $(m_1 + m_2)\ell^2$
24.	A solid sphere is in well as rotational ki	rolling motion. In rolling netic energy (Kr) simulta	motion a body posses aneously. The ratio K_t :	ses translational kinetic energy (K_t) as ($K_t + R_r$) for the sphere is :
	(1) 7 : 10	(2) 2 : 5	(3) 10 : 7	(4) 5 : 7
25.	A solid sphere is r increased keeping the sphere ?	otating freely about its its mass same. Which o	symmetry axis in free of the following physica	e space. The radius of the sphere is al quantities would remain constant for [NEET 2018]
	(1) Angular velocity(3) Rotational kinetional	c energy	(2) Angular mom (4) Moment of in	entum ertia
26.	A student measured main scale reading reference level. If s	d the diameter of a sma is 5 mm and zero of crew gauge has a zero	Il steel ball using a scre circular scale division error of –0.004 cm, the	ew gauge of least count 0.001 cm. The coincides with 25 divisions above the correct diameter of the ball is
	(1) 0.521 cm	(2) 0.529 cm	(3) 0.053 cm	(4) 0.525 cm
27.	A solid cylinder of n required to stop afte	nass 2 kg and radius 4 $α$ er 2π revolutions is:	cm rotating about its ax	tis at the rate of 3 rpm. The torque [NEET-2019-I]
	(1) 2×10^6 Nm	(2) 2 × 10 ^{−6} Nm	(3) 2 × 10 ^{−3} Nm	(4) 12 × 10 ⁻⁴ Nm

٠

(1) 2.2 m

28.	A disc of radius 2 m and mass 100 kg rolls on a horizontal floor. Its centre of mass has speed of 20 cm/s					
	How much wor	k is needed to stop it?		[NEET-2019-I]		
	(1) 1 J	(2) 3 J	(3) 30 kJ	(4) 2 J		
29.	A solid cylinder of mass 2 kg and radius 50 cm rolls up an inclined plane of angle of inclination 30°. The					
	centre of mass	of the cylinder has speed	d of 4 m/s. The distance to	avelled by the cylinder o	n the inclined	

surface will be, [take $g = 10 \text{ m/s}^2$]

(2) 1.6 m

(3) 1.2 m (4) 2.4 m

PART - II : JEE (MAIN) / AIEEE PROBLEMS (PREVIOUS YEARS)

1. A thin uniform rod of length l and mass m is swinging freely about a horizontal axis passing through its end. Its maximum angular speed is ω . Its cenfre of mass rises to a maximum height of :

			[AIEEE-2009, 4/14	14]
$1 \ell \omega$	$1 \ell^2 \omega^2$	$1 l^2 \omega^2$	$1 \ell^2 \omega^2$	
(1) ⁶ g	(2) 2 g	(3) ⁶ g	(4) ³ g	

2. A thin horizontal circular disc is rotating about a vertical axis passing through its centre. An insect is at rest at a point near the rim of the disc. The insect now moves along a diameter of the disc to reach its other end. During the journey of the insect, the angular speed of the disc : [AIFEE-2011. 1-May; 4/120, –1]

(1) remains unchanged	(2) continuously decreases
(3) continuously increases	(4) first increases and then decreases

3. A pulley of radius 2m is rotated about its axis by a force $F = (20t - 5t_2)$ newton (where t is measured in seconds) applied tangentially. If the moment of inertia of the pulley about its axis of rotation is 10 kg m₂, the number of rotations made by the pulley before its direction of motion if reversed, is :

(1) less than 3 (3) more than 6 but less than 9

[AIEEE - 2011, 1-May; 4/120, -1] (2) more than 3 but less than 6 (4) more than 9

[NEET-2019-II]

A mass 'm' supported by a massless string wound around a uniform hollow cylinder of mass m and radius 4. R. If the string does not slip on the cylinder, with what acceleration will the mass fall on release ? [JEE (Main)-2014]

R 2g g 3 (2) 2 6 (1) (3)(4) g

- 5. A bob of mass m attached to an inextensible string of length l is suspended from a vertical support. The bob rotates in a horizontal circle with a angular speed ω rad/s about the vertical. About the point of suspension : [JEE (Main) 2014]
 - (1) angular momentum is conserved.
 - (2) angular momentum changes in magnitude but not in direction
 - (3) angular momentum changes in direction but not in magnitude.

- (4) angular momentum changes both in direction and magnitude.
- 6. Form a solid sphere of mass M and radius R a cube of maximum possible volume is cut. Moment of inertia of cube about an axis passing through its centre and perpendicular to one of its faces is IJEE(Main)-2015: 4/120. –11

(1)
$$\frac{MR^2}{32\sqrt{2}\pi}$$
 (2) $\frac{MR^2}{16\sqrt{2}\pi}$ (3) $\frac{4MR^2}{9\sqrt{3}\pi}$ (4) $\frac{4MR^2}{3\sqrt{3}\pi}$

7. A particle of mass m is moving along the side of square of side 'a' with a uniform speed v in the x-y plane as shown in the figure : [JEE Main 2016]



Which of the following statements is false for the angular momentum L about the origin ?

(1)

$$\vec{L} = mv \left[\frac{R}{\sqrt{2}} - a \right] \hat{k}$$
when the particle is moving from C to D.

$$\vec{L} = mv \left[\frac{R}{\sqrt{2}} + a \right] \hat{k}$$
when the particle is moving from B to C.
(3)

$$\vec{L} = \frac{mv}{\sqrt{2}} R \quad \hat{k}$$
when the particle is moving from D to A.

$$\vec{L} = -\frac{mv}{\sqrt{2}} R \quad \hat{k}$$
when the particle is moving from A to B.

8. A roller is made by joining together two cones at their vertices O. It is kept on two rails AB and CD which are placed asymmetrically (see figure), with its axis perpendicular to CD and its centre O at the centre of line joining AB and CD (see figure). It is given a light push so that it starts rolling with its centre O moving parallel to CD in the direction shown. As it moves, the roller will tend to : [JEE Main 2016]



(1) turn right

(3) turn left and right alternately

(4) turn left.

9. The moment of inertia of a uniform cylinder of length *l* and radius R about its perpendicular bisector is I. What is the ratio *l*/R such that the moment of inertia is minimum? [JEE Main 2017]

10. A slender uniform rod of mass M and length *l* is pivoted at one end so that it can rotate in a vertical plane (see figure). There is negligible friction at the pivot. The free end is held vertically above the pivot and then released, the angular acceleration of the rod when it makes an angle θ with the vertical is.

[JEE Main 2017]



11. Seven identical circular planar disks, each of mass M and radius R are welded symmetrically as shown. The moment of inertia of the arrangement about the axis normal to the plane and passing through the point P is : [JEE-Main-2018]





From a uniform circular disc of radius R and mass 9 M, a small disc of radius $\overline{3}$ is removed as shown in 12. the figure. The moment of inertia of the remaining disc about an axis perpendicular to the plane of the disc and passing through centre of disc is : [JEE-Main-2018]

R

(4) $\frac{40}{9}$ MR²



(3) 4 MR²

(1) 10 MR²

13. An equilateral triangle ABC is cut from a thin solid sheet of wood. (See figure) D, E and F are the midpoints of its sides as shown and G is the centre of the triangle. The moment of inertia of the triangle about an axis passing through G and perpendicular to the plane of the triangle is I₀. If the smaller triangle DEF is removed from ABC, the moment of inertia of the remaining figure about the same axis is I. Then : [JEE-Main-2019]



14. An L-shaped object, made of thin rods of uniform mass density, is suspended with a string as shown in figure. If AB = BC, and the angle made by AB with downward vertical is θ, then : **[JEE-Main-2019]**



15. A rod of length 50 cm is pivoted at one end. It is raised such that if makes an angle of 30° from the
horizontal as shown and released from rest. Its angular speed when it passes through the horizontal (in
rad s⁻¹) will be (g = 10 m/s⁻²)[JEE-Main-2019]



16. To mop-clean a floor, a cleaning machine presses a circular mop of radius R vertically down with a total force F and rotates it with a constant angular speed about its axis. If the force F is distributed uniformly over the mop and if coefficient of friction between the mop and the floor is μ, the torque, applied by the machine on the mop is : [JEE-Main-2019]

μFR	2 ER	μFR	μFR
(1) 3	(2) $\frac{3}{3}$	(3) 2	(4) 6

17. A homogeneous solid cylindrical roller of radius R and mass M is pulled on a cricket pitch by a horizontal force. Assuming rolling without slipping, angular acceleration of the cylinder is :



A rigid massless rod of length 3ℓ has two masses attached at eachend as shown in the figure. The rod is pivoted at pont P on the horizontal axis (see figure). When released from initial horizontal position, its instantaneous angluar acceleration will be : [JEE-Main-2019]



19. A circular disc D_1 of mass M and radius R has two identical discs D_2 and D_3 of the same mass M and
radius R attached rigidly at its opposite ends (see figure.) The moment of inertia of the system about the
axis OO', passing through the centre of D_v as shown in the figure, will be:[JEE-Main-2019]



20. A string is wound around a hollow cylinder of mass 5 kg and radius 0.5 m. If the string is now pulled with a horizontal force of 40 N, and the cylinder is rolling without slipping on a horizontal surface (see figure), then the angular acceleration of the cylinder will be (Neglect the mass and thickness of the string): [JEE-Main-2019]



The magnitude of torque on a particle of mass 1 kg is 2.5 Nm about the origin. If the force acting on it is 1 N, and the distance of the particle from the origin is 5 m, the angle between the force and the position vector is (in radians) :

π	π	π	π
(1) 6	(2) 4	(3) 8	(4) 3

point O will be

22. A slab is subjected to two forces \vec{F}_1 and \vec{F}_2 of same magnitude F as shown in the figure. Force \vec{F}_2 is in XY-plane while force \vec{F}_1 acts along z-axis at the point $(2\vec{i}+3\vec{j})$. The moment of these forces about

[JEE-Main-2019]



23. A particle of mass 20 g is released with an initial velocity 5 m/s along the curve from the point A, as shown in figure. The point A is at height h from point B. The particle sides along the frictionless surface. When the particle reaches point B, its angular momentum about O will be : [JEE-Main-2019]



24. The moment of inertia of a solid sphere, about an axis parallel to its diameter and at a distance of x from it, is I(x). Which one of the graphs represents the variation of I(x) with x correctly?



25. Let the moment of inertia of a hollow cylinder of length 30 cm (inner radius 10 cm and outer radius 20 cm), about its axis be I. The radius of a thin cylinder of the same mass such that its moment of inertia about its axis is also I, is: [JEE-Main-2019]
 (1) 14 cm
 (2) 16 cm
 (3) 18 cm
 (4) 12 cm

		ISV	lers	;=									
SECT	ION (A)	:					CISE	- 1					
1.	(3)	2.	(4)	3.	(3)	4.	(2)	5.	(2)	6.	(3)	7.	(2)
SECT	ION (B) :	2	(2)	2	(3)	Л	(1)	5	(1)	6	(1)	7	(2)
8.	(2) (4)	2. 9.	(2)	3. 10.	(3)	4. 11	(4)	J. 12	(4)	13.	(1)	7. 14.	(2)
15.	(2)	16.	(2)	17.	(1)	18.	(1)	19.	(4)	20.	(1)	21.	(3)
22. 29	(1)	23. 30	(2)	24. 31	(1)	25. 32	(2)	26. 33	(1)	27. 34	(4) (4)	28. 35	(2)
36.	(1)	37.	(1)	38.	(1)	39.	(1)	40.	(3)	41.	(3)	42.	(4)
43.	(2)	44.	(2)	45.	(3)	46.	(4)	47.	(4)	48.	(3)	49.	(3)
SECT	ION (C) : (2)	2	(2)	3	(1)	4	(1)	5	(1)	6	(3)	7	(3)
8.	(3)	<u>9</u> .	(1)	10.	(4)		(1)	5.	(')	0.	(0)		(0)
SECT	ION (D) :	~		•				_					
1. SECT	(2) ION (F) ·	2.	(1)	3.	(3)	4.	(3)	5.	(2)	6.	(3)		
1.	(4)	2.	(1)	3.	(2)	4.	(1)	5.	(3)	6.	(3)		
SECT	ION (F) :	•	(0)	•			(0)	-	(0)	•		-	$\langle \mathbf{O} \rangle$
1. 8	(3)	2. 9	(2) (4)	3. 10	(1)	4. 11	(2)	5. 12	(3)	6.	(4)	7.	(3)
SECT			()	10.	(0)	• • •	(2)	121	(2)				
1.	(1)	2.	(4)	3.	(3)	4.	(2)	5.	(2)	6.	(4)	7.	(4)
8. 15	(3)	9. 16	(2)	10. 17	(1) (4)	11. 18	(1) (4)	12. 19	(4)	13. 20	(3)	14. 21	(3)
22.	(4)	23.	(0)	24.	(1)	25.	(4)	26.	(1)	27.	(4)	28.	(3)
29.	(2)	30.	(4)	31.	(3)	32.	(3)	33.	(1)	34.	(3)	35.	(1)
36. SECT	(2) ION (H) :	37.	(2)										
1.	(2)	2.	(4)	3.	(2)	4.	(2)	5.	(2)	6.	(1)	7.	(1)
8. 45	(2)	9.	(2)	10.	(2)	11.	(3)	12.	(1)	13.	(2)	14.	(2)
15. 22.	(2)	16. 23.	(2)	24.	(4) (4)	18. 25.	(2)	19. 26.	(3)	20. 27.	(3)	21.	(4)
SECT	ION (I) :		(-)		(')		(0)		(0)		(-)		
1.	(1)	2.	(1)	3.	(3)	4.	(4)	5.	(1)	6.	(3)	7.	(2)
ð. SECT	(2) ION (J) :	9.	(4)	10.	(4)	11.	(1)	12.	(4)	13.	(1)	14.	(1)
1.	(4)	2.	(1)	3.	(2)	4.	(3)	5.	(4)				
SECT	ION (K) :	2	(2)										
1.	(1)	Ζ.	(3)					# ว					
1.	(1)	2.	(1)	3	(4)			π ∠ 5	(1)	6	(2)	7	(4)
8.	(2)	9.	(1)	10.	(4)	11.	(1)	12.	(4)	13.	(1)	14.	(2)
15.	(1)	16.	(4)	17.	(4)	18.	(1)	19. 20	(4)	20.	(3)	21.	(4)
<u> 22.</u>	(1)	23.	(2)	24.	(4)			26. # ว	(4)	21.	(3)		
1.	(3)	2.	(1)	3.	(1)	га 4.	(1)	5.	(2)	6.	(2)	7.	(2)
8.	(1)	9.	(3)	10.	(1)	11.	(3)	12.	(4)	13.	(4)	14.	(3)
15. 22	(3) (3)	16. 23	(3)	17. 24	(4) (4)	18. 25	(3)	19. 26	(3)	20. 27	(2) (2)	21. 28	(4) (2)
29.	(4)	23.	(~)	<u> 4</u> 7.	()	£J.	(4)	20.	(4)	£1.	(~)	20.	(4)
PART – II													
1. 8	(3) (4)	2. 9	(4) (2)	3. 10	(2) (2)	4. 11	(2) (2)	5. 12	(3) (3)	6. 13	(3) (2)	7. 14	(1) (2)
15.	(1)	16.	(2)	17.	(4)	18.	(2)	19.	(3)	20.	(2)	21.	(1)
22.	(4)	23.	(2)	24.	(2)	25.	(2)						