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#### IMPORTANT FACTS AND FORMULAE FOR JEE

#### **AIEEE - PHYSICS**

#### **UNITS & MEASUREMENT**

1. If  $x = a^m b^n c^p$ ,

then fractional error in 'x' can be calculated as

$$\frac{\Delta x}{x} = m\frac{\Delta a}{a} + n\frac{\Delta b}{b} + p\frac{\Delta c}{c}.$$

2. For vernier callipers, least count = s - v.

> (s = length of one division on main scale, v = length of one division on vernier scale.)

- 3. Length measured by vernier calliper = reading of main scale + reading of vernier scale × least count.
- pitch of the screw For Screw Gauge, least count =  $\frac{\text{pitch of the screw}}{\text{no. of divisions on the circular scale}}$ . 4.

where, Pitch =  $\frac{\text{distance travelled on the pitch scale}}{\frac{1}{2}}$ no. of rotations

5. Length measured by screw gauge = Reading of main scale + Reading of circular scale × least count.

#### MOTION IN ONE DIMENSION

1.

2.

t1	=	initial time,			t <b>2</b>	=	final time
u	=	initial veloc	ity,		v	=	final velocity
$V_{\boldsymbol{av}}$	=	average velo	ocity		а	=	acceleration
S	=	net displace	ement/	distance			
Aver	age spo	eed, v <sub>av</sub>	=	total distar t <sub>2</sub>	nce tra – t <sub>1</sub>	welled	
Insta	antaneo	ous speed, v	=	$\lim_{\Delta t \to \infty} \left( \frac{\Delta s}{\Delta t} \right) =$	$= \left  \frac{ds}{dt} \right $		

**3.** Displacement =  $\int_{t_1}^{t_2} \overrightarrow{v} dt$ 

**4.** Total distance = 
$$\int_{t_1}^{t_2} |v| dt$$

5. 
$$a = \frac{dv}{dt} = v\frac{dv}{ds} = \frac{d^2s}{dt^2}$$

**6.** When acceleration is constant,

$$V = u + at$$
,  $s = ut + \frac{1}{2}at^2$  &  $v^2 = u^2 + 2as$ 

## MOTION IN TWO AND THREE DIMENSION

- $\omega$  = angular velocity,  $\alpha$  = angular acceleration,
- $a_{\tau}$  = tangential acceleration,  $a_{N}$  = normal acceleration
- R = radius of curvature

## Vectors

**1.** 
$$\overrightarrow{R} = \sqrt{P^2 + Q^2 + 2PQ\cos\theta}$$

Where ' $\theta$  ' is angle between the vectors and direction of  $\stackrel{\rightarrow}{R}$  from  $\stackrel{\rightarrow}{P}$  ,



$$\phi = \tan^{-1} \frac{Q \sin \theta}{P + Q \cos \theta}$$

**2.** Two vectors  $\vec{a} \left( a_1 \hat{i} + a_2 \hat{j} a_3 \hat{k} \right)$  and  $\vec{b} \left( b_1 \hat{i} + b_2 \hat{j} b_3 \hat{k} \right)$  are equal if :

$$a_1 = b_1,$$

=  $b_2$  and a**2** bз aз = If angle between two vectors  $\stackrel{\rightarrow}{a}$  and  $\stackrel{\rightarrow}{b}$  is ' $\theta$ ' 3.  $\stackrel{\rightarrow}{a} \stackrel{\rightarrow}{\cdot} \stackrel{\rightarrow}{b}$ ab  $\cos\theta$  and =  $\overrightarrow{a} \times \overrightarrow{b} =$ (ab sin  $\theta$ ) $\hat{n}$ , ( $\hat{n}$  is unit vector perpendicular to both  $\hat{a}$  and  $\hat{b}$ ) 4. Velocity of 'B' with respect to 'A',  $\overrightarrow{V}_{\mathbf{B}} - \overrightarrow{V}_{\mathbf{A}}$  $\overline{V}_{BA}$  = **Projectile Motion**  $2u\sin\theta$ Time of flight, 5. to = g  $R = \frac{u^2 \sin 2\theta}{g}$ 6. Range,  $\frac{\mathrm{u}^{\mathbf{2}}\sin^{\mathbf{2}}\theta}{2\mathrm{g}}$ = Н 7. Maximum height,  $\left(u\cos\theta t, u\sin\theta t - \frac{1}{2}gt^{2}\right)$ (x, y) = 8. Equation of projectile, y =  $x \tan \theta - \frac{g x^2}{2u^2 \cos^2 \theta}$ 9. **Circular Motion**  $\lim_{\Delta t\to 0}\frac{\Delta\theta}{\Delta t}$ dθ 10. ω = dt ſθ  $d\boldsymbol{\omega}$  $d^2\theta$ α  $dt^2$ dt

dv 11. a, = dt  $\frac{V^2}{R}$ a<sub>N</sub> =  $\sqrt{a_{\tau}^{2}+a_{N}^{2}}$ a<sub>Total</sub> =  $\frac{\left(1 + \left(\frac{dt}{dx}\right)^2\right)^{3/2}}{\frac{d^2y}{dx^2}}$ R at (x, y) 12. = Banking of roads, 13.  $\frac{v^{\mathbf{2}}}{rg}$  $\tan \theta =$ Centripetal force =  $\frac{mv^2}{r} = mr\omega^2$ 14. LAWS OF MOTION F - R = ma→ a → F 1. R 🗲 •  $\mu_{{\bf s}}N$ 2. ≻ F f  $\mu_{\mathbf{k}}N$ F٠

where f is the frictional force.

**3.** 
$$\frac{\Delta p}{\Delta t}$$
 = F  
**4.**  $\vec{P}$  =  $\sum m_i \vec{V}_i$ 

#### WORK, ENERGY AND POWER

- **1.** Total energy = kinetic energy + potential energy
- **2.** Kinetic Energy =  $\frac{1}{2}$  mv<sup>2</sup>, Potential Energy = mgh
- **3.**  $\int dW = \int_{i}^{f} \vec{F} \cdot d\vec{r}$
- Conservative forces : spring force, electrostatic force, gravitation force
   Non-conservative forces : frictional force, viscous force
- **5.** For elastic collision.

$$M_{1}u_{1} + m_{2}u_{2} = m_{1}v_{1} + m_{2}v_{2}$$
$$\frac{1}{2}m_{1}u_{1}^{2} + \frac{1}{2}m_{2}u_{2}^{2} = \frac{1}{2}m_{1}v_{1}^{2} + \frac{1}{2}m_{2}v_{2}^{2}$$

**6.** For perfectly inelastic collision,

$$= \frac{m_{1}u_{1} + m_{2}u_{2}}{m_{1} + m_{2}}$$

If coefficient of restitution is e (0 < e < 1),</li>
 Velocity of separation = e (velocity of approach)

8. Impulse =  $\int_{t_1}^{t_2} \vec{F} dt = \vec{P_2} - \vec{P_1}$ 

#### **ROTATIONAL MOTION AND MOMENT OF INERTIA**

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 $\tau$  = torque, F = force I = moment of inertia  $\alpha$  = angular acceleration L = angular momentum  $a_{CM}$  = acceleration of centra of mass

**1.** 
$$\overrightarrow{R}_{CM} = \frac{\sum_{i} \overrightarrow{m_{i} r_{i}}}{M}$$

$$2. r_{CM} = \frac{1}{M} \int r \ dm$$

- **3.**  $\stackrel{\rightarrow}{\tau} = \stackrel{\rightarrow}{r \times F}$
- **4.** Moment of inertia,

I = 
$$\sum_{i} m_{i} r_{i}^{2} = \int r^{2} dm$$
  
 $\overrightarrow{\tau_{ext}} = I \overrightarrow{\alpha}$ 

**5.** Angular momentum,

$$\vec{L} = \vec{r} \times \vec{p}$$

$$\vec{L} = \vec{I} \cdot \vec{\omega}$$

**6.** 
$$\frac{d \overrightarrow{L}}{dt} = \overline{\tau_{ext}}$$

7.	(i)	Pure translation	$\rightarrow$	$\overrightarrow{\tau_{CM}} = 0$
	(ii)	Rotation	$\rightarrow$	$\overrightarrow{\tau_{\mathbf{CM}}} \neq 0$
	(iii)	Pure rotation	$\rightarrow$	$\sum \vec{F} = 0, \ \vec{\tau_{CM}} \neq 0$
	(iv)	Translation	$\rightarrow$	$\sum \vec{F} \neq 0$
	(v)	Rolling	$\rightarrow$	$a_{CM} = \alpha r, V_{CM} = \omega r$
	(vi)	Sliding or sliding	$\rightarrow$	$a_{CM} \neq \alpha r, V_{CM} \neq \omega r$

1.	Very thin circular hoop	R	MR <sup>2</sup>
2.	Uniform solid cylinder about it's symmetry axis	<u> </u>	$\frac{1}{2}$ MR <sup>2</sup>
3.	Uniform solid sphere about it's diameter		$\frac{2}{5}$ MR <sup>2</sup>
4.	Uniform hollow sphere about it's diameter		$\frac{2}{3}$ MR <sup>2</sup>
5.	Uniform thin rod about it's centre and perpendicular to it		$\frac{M\ell^2}{12}$
6.	Thin rectangular sheet about an axis perpendicular to sheet and passing through it's centre		$\frac{M(a^2+b^2)}{12}$
7.	Uniform solid right cone about it's axis	R	$\left(\frac{3}{10}\right)$ MR <sup>2</sup>
8.	Uniform hollow right cone about it's axis	R	$\frac{1}{2}$ MR <sup>2</sup>

# Table for standard moments of inertia :

# GRAVITATION

- G = Universal gravitational constant,
- U = Gravitational potential energy
- V = Gravitational potential,

E = Gravitational field E F = Gravitational force  $F = G \frac{Mm}{r^2}$ 1. (attraction force) Gravitational potential energy,  $V = -G \frac{m_1 m_2}{r}$ 2.  $U_{f} - U_{i} = -\int_{r}^{f} \vec{F} \cdot d\vec{r}$ З. Gravitational potential,  $V = -\frac{GM}{r}$ 4. Gravitational field,  $E = \frac{F}{m} = \frac{GM}{r^2}$ 5.  $u \geq \sqrt{\frac{2GM}{R}}$ Escape velocity, 6. (i)  $g' = g\left(1 - \frac{h}{R_{o}}\right)$ , where 'h' is depth from the earth's surface. 7. (ii)  $g' = \frac{g}{\left(1 + \frac{h}{R_e}\right)^2}$ , where 'h' is height from the earth's surface.

**8.** v = 
$$\sqrt{\frac{GM}{r}}$$

**9.** T = 
$$2\pi\sqrt{\frac{r^3}{GM}}$$

K.E. =  $\frac{\text{GMm}}{2\text{a}}$ , PK.E. =  $-\frac{\text{GMm}}{\text{a}} \Rightarrow$  E =  $-\frac{\text{GMm}}{2\text{a}}$ 10. Gravitational field,  $E = \frac{F}{m} = \frac{GM}{r^2}$ 11.

Uniform solid sphere (i)

$$E(r) = \frac{GMr}{R^3}, \quad r < R$$
$$E(r) = \frac{GM}{R^2}, \quad r = R$$
$$E(r) = \frac{GM}{r^2}, \quad r > R$$

$$V(\mathbf{r}) = -\frac{\mathrm{GM}}{\mathrm{R}} \left[ \frac{3}{2} - \frac{1}{2} \frac{\mathbf{r}^2}{\mathrm{R}^2} \right], \quad \mathbf{r} < \mathrm{R}$$
$$V(\mathbf{r}) = -\frac{\mathrm{GM}}{\mathrm{R}}, \quad \mathbf{r} = \mathrm{R}$$

$$V(r) = -\frac{GM}{r},$$

۰,

$$E(r) = 0, \quad r < R$$

$$E(r) = \frac{GM}{R^2}, \quad r = R$$

$$E(r) = \frac{GM}{r^2}, \quad r > R$$

$$V(r) = -\frac{GM}{R}, \quad r < R$$

$$V(r) = -\frac{GM}{r}, \quad r > R$$



r > R

Uniform circular ring at point on axis : (iii)

$$E(\mathbf{r}) = \frac{GMr}{\left(R^{2} + r^{2}\right)^{3/2}}$$

$$V(\mathbf{r}) = -\frac{2GM}{R^{2}} \left[\sqrt{R^{2} + r^{2}} - P\right]$$

$$R = -\frac{2GM}{R^{2}} \left[\sqrt{R^{2} + r^{2}} - P\right]$$

# SOLIDS AND FLUIDS

SOLI	70 M					
	р	=	pressure,	ρ	=	density
	V	=	volume of solids,	v	=	volume immersed
	D	=	density of solid,	d	=	density of liquid
	А	=	cross section area	U	=	upthrust
	Y	=	Young's modulus,	σ	=	stress
	3	=	strain	В	=	Bulk modulus
	F	=	force	А	=	cross section area
	$\ell$	=	initial length	$\Delta \ell$	=	change in length
	Т	=	surface tension,	R	=	radius of the bubble/drop
	r	=	radius of the tube	θ	=	angle of contact
	η	=	coefficient of viscosity,	F	=	force
1.	р	=	$\lim_{\Delta S \to c} \frac{F}{\Delta S}$			
2.	Variation of pressure with height, dP = $-\rho$ g dh					
3.	Arcl	nim	edes Principle, mg = v	dg d	or V.	D = dv
4.	Equation of continuity, $A_1v_1 = A_2v_2$					
5.	Bernoulli's equation, $P + \frac{1}{2}pv^2 + \rho gh = constant$					
6.	$Y = \frac{\sigma}{\varepsilon} = \frac{F\ell}{A\Delta\ell}$					
7.	Bull	k m	odulus, $B = -\frac{\Delta x}{\Delta x}$	ΔΡ 7 / V		
8.	Elas	stic	potential energy = $\frac{1}{2} \times \frac{1}{2}$	stres	s × st	rain × volume

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Excess pressure inside a drop,  $\Delta P = \frac{2T}{R}$ 9. Excess pressure inside a soap bubble,  $\Delta P = \frac{4T}{R}$ 10. Rise of liquid in a capillary tube,  $h = \frac{2T\cos\theta}{r \rho g}$ 11.  $F = -\eta A \frac{dv}{dz}$ 12. Stoke's law, F =  $6\pi r\eta v$ 13. Terminal velocity,  $v_0 = \frac{2r^2(\rho - \sigma)g}{9\eta}$ 14. where, v = velocity,  $\sigma = density$  of liquid,  $\rho = density$  of solid Velocity of efflux = V =  $\sqrt{2gh}$ 15. **OSCILLATIONS** angular frequency, I = moment of inertia ω =

T = time period,  $\ell$  = length of pendulum

$$1. \qquad \frac{d^2x}{dt^2} + \omega^2 x = 0$$

**2.** 
$$T = \frac{2\pi}{\omega}$$

- 3. Simple pendulum,  $T = 2\pi \sqrt{\ell/g}$ ,  $\omega = \sqrt{g/\ell}$
- **4.** Angular simple harmonic motion,

$$T = 2\pi \sqrt{I/k}$$
,  $\omega = \sqrt{\frac{k}{I}}$ 

**5.** Physical pendulum

$$T = 2\pi \sqrt{\frac{I}{mg\ell}}$$
,  $\omega = \sqrt{\frac{mg\ell}{I}}$ 



i) Parallel  $K_{eff} = K_1 + K_2$ 

- **7.** Effective spring constant
  - i) Parallel k<sub>eff</sub> = k<sub>1</sub> + k<sub>2</sub> ii) Series

$$\frac{1}{k_{\text{eff}}} = \frac{1}{k_1} + \frac{1}{k_2}$$

$$\begin{array}{c|c} & & & \\ & & & & \\ & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & &$$

## WAVES

А	= amplitude	$\mu$ = mass per unit length
у	= displacement	$\omega$ = angular frequency
Δφ	= phase difference	$\Delta x$ = path difference
ν	= frequency	$\lambda$ = wavelength
L	= length of the wire	

**1.** Equation of wave,

$$\mathbf{y} = \mathbf{A} \, \sin \, \boldsymbol{\omega} \left( \mathbf{t} - \frac{\mathbf{x}}{\mathbf{v}} \right)$$

**2.** Velocity of a wave on a string,

$$v = \sqrt{\frac{F}{\mu}}$$
 ( $\mu$  = mass per unit length)

$$\mathbf{3.} \qquad \mathbf{P_{av}} = 2\pi^2 \mu \mathbf{v} \mathbf{A^2} \boldsymbol{\gamma^2}$$

4.

$y_1 = a_1 \sin \omega t$ ,	$y_2 = a_2 \sin(\omega t + \phi)$
resultant wave,	$\mathbf{y} = \mathbf{y_1} + \mathbf{y_2}$
consecutive interference,	$\Delta \phi = 2n\pi$ or $\Delta x = n\lambda$
destructive interference,	$\Delta \phi = (2n-1)\pi$ or $\Delta x = \left(n-\frac{1}{2}\right)\lambda$
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5. 
$$\mathbf{v_0} = \frac{1}{2L} \sqrt{\frac{F}{\mu}}$$
,  $(\mathbf{v_0} = \text{fundamental frequency})$   
6. Speed of sound in fluid  $= \sqrt{\frac{B}{\rho}}$  (B = Bulk modules  $\rho$  = density)  
7. Speed of sound in solid  $= \sqrt{\frac{Y}{\rho}}$  (Y = Young's modules  $\rho$  = density)  
8. Speed of sound in gas  $= \sqrt{\frac{YP}{\rho}}$ ,  $\mathbf{va}\sqrt{T}$   
9. Closed organ pipe,  $\mathbf{v} = (2n+1)\frac{\mathbf{v}}{4\ell}$   
10. Open organ pipe,  $\mathbf{v} = \frac{n\mathbf{v}}{\ell}$   
11. Frequency of beats  $= |\mathbf{v_1} - \mathbf{v_2}|$   
12. Doppler effect,  $\mathbf{v} = \frac{\mathbf{v} + \mathbf{u_0}}{\mathbf{v} - \mathbf{u_s}} \mathbf{v_0}$ 

# HEAT AND THERMODYNAMICS

Р	= pressure	V	=	volume
n	= no. of moles	Т	=	temperature
R	= universal gas constant	α	=	coefficient of linear expansion
β	<ul> <li>coefficient of superficial expansion</li> </ul>	γ	=	coefficient of volume expansion
Q	= heat taken/supplied	s	=	specific heat
m	= mass	Δθ	=	change in temperature
L	<ul> <li>latent heat of state change per mass</li> </ul>	W	=	work done by gas
U	= internal energy	$V_{\mathbf{i}}$	=	initial volume
Vf	= final volume	$\mathrm{P}_{\mathbf{i}}$	=	initial pressure
P <sub>f</sub>	= final pressure			

**1.** Ideal gas equation, PV = n R T

**2.** Thermal expansion, 
$$\boldsymbol{\alpha} = \frac{1}{L} \frac{dL}{dT}; \quad \boldsymbol{\gamma} = \frac{1}{V} \frac{dV}{dT}$$

**3.** 
$$v_{rms} = \sqrt{\frac{3PV}{M}} = \sqrt{\frac{3RT}{M_0}}$$

Translational kinetic energy,

$$\mathbf{k} = \frac{3}{2} \text{ PV}$$
$$\overline{\mathbf{v}} = \sqrt{\frac{8RT}{\pi M_0}} \quad ; \quad \mathbf{v_p} = \sqrt{\frac{2RT}{M_0}}$$

**4.** Vander Waals equation :

$$\left(P + \frac{n^2 a}{V^2}\right) (V - nb) = nRT$$

- **5.**  $Q = ms \Delta \theta$
- 6. Latent heat of state change,Q = mL

$$\mathbf{7.} \qquad \mathrm{dQ} = \mathrm{dW} + \mathrm{dU}$$

**8.** Work done by a gas,

$$W = \int_{\mathbf{v_1}}^{\mathbf{v_2}} P \, dV$$

**9.** Work done on an ideal gas :

isothermal process, W = nRT  $ln\left(\frac{V_{f}}{V_{i}}\right)$ isobaric process, W = P(V\_{f} - V\_{i}) isochoric process, W = 0 adiabatic process, W =  $\frac{P_{i}V_{i} - P_{f}V_{f}}{\gamma - 1}$ 

**10.** Entropy,

$$\Delta S = \frac{\Delta Q}{T}$$

**11.** Efficiency of an ideal reversible heat engine,

$$\boldsymbol{\eta} = \boldsymbol{1} - \frac{T_{\boldsymbol{2}}}{T_{\boldsymbol{1}}}$$

12.  $C_{\mathbf{v}} = \left(\frac{\Delta Q}{n\Delta T}\right)$  constant volume  $C_{\mathbf{P}} = \left(\frac{\Delta Q}{n\Delta T}\right)$  constant pressure

**13.** 
$$dU = nC_v dT$$

$$14. \quad C_p - C_v = R, \ \frac{C_p}{C_v} = \gamma$$

**15.** Adiabatic process,  $PV^{\gamma}$  = constant

## TRANSFERENCE OF HEAT

	e = Coefficient of emission $\sigma$ = Stefan's constant
	K = Coefficient of thermal A = Area conductivity
1.	$\frac{\Delta Q}{\Delta t} = K \frac{A(T_1 - T_2)}{x} = -KA \frac{dT}{dx}$
2.	Thermal resistance, R = $\frac{x}{KA}$
	Heat current, I = $\frac{T_1 - T_2}{R}$
3.	Series connection, $R = R_1 + R_2$
	Parallel connection, $1/R = 1/R_1 + 1/R_2$
4.	$U = e \sigma AT^4$ , (U = energy emitted per second)
5.	Newton's law of cooling,
	$\frac{d\boldsymbol{\theta}}{dt} = -K(\boldsymbol{\theta} - \boldsymbol{\theta_0}) \qquad (\boldsymbol{\theta} \text{ taken in Celsius scale})$

## ELECTROSTATICS

#### Facts :

- **1.** Charge is quantized.
- **2.** Charge is conversed, net charge does not change.
- **3.** The tangent to a line of force at any point gives the direction of electric filed at that point.
- **4.** No electric filed exists inside conductors.
- **5.** Electric fields at surfaces of conductors are perpendicular to surface.
- **6.** All points on or inside a conductors are at the same potential.
- **7.** In isolated capacitor, charge does not change.
- **8.** Capacitors in series have equal amount of charges.
- **9.** The voltage across two capacitor connected in parallel is same.
- **10.** In steady state no current flows through a capacitor.

F	=	force	q	=	charge
λ	=	linear charge density	С	=	capacitance
V	=	electric potential	Е	=	electric filed
σ	=	surface charge density	ρ	=	volume charge density
U	=	electrical potential energy	r	=	distance
$q_{\textbf{enc}}$	=	charge enclosed	р	=	dipole moment

**1.** Coulombs law : The force between two point charges at rest,

$$\vec{F} = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r^2} \hat{r}$$

**2.** Electric field :

$$\vec{F} = q \vec{E}$$

**3.** Electric Potential :

 $\Delta V = - \mathbf{E} \ \Delta \ r \cos \theta$ 

$$V = -\int_{\infty}^{r} \vec{E} \cdot d \vec{r}$$

**4.** Electric Potential Energy :

$$U = \frac{1}{4\pi\epsilon_0} \sum_{\mathbf{i} < \mathbf{j}} \frac{\mathbf{q}_{\mathbf{i}} \mathbf{q}_{\mathbf{j}}}{\mathbf{r}_{\mathbf{i}\mathbf{j}}}$$

**5.** Fields for a point charge :

$$E = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2};$$
$$V = \frac{1}{4\pi\epsilon_0} \frac{q}{r},$$

Gauss's law : net electric flex through any closed surface is equal to the net charge enclosed by thee surface divided by  $\epsilon_0$ .

$$\oint_{\mathbf{s}} \vec{E} \cdot \vec{ds} = \frac{q_{enc}}{\varepsilon_0}$$

Electric Dipole : It is a combination of equal and opposite charges.

Electric dipole moment  $\vec{P} = q \vec{d}$ , where d is the separation between the two point charges.

## Electric field due to various charge distribution :

a) If the line charge is  $\lambda'$  then

i) electric field outside cylinder (Radius 'R')

$$\mathbf{E} = \frac{\boldsymbol{\lambda}}{2\boldsymbol{\pi}\boldsymbol{\varepsilon_0}\mathbf{r}}$$

ii) electric filed on the surface

$$\mathbf{E} = \frac{\mathbf{\lambda}}{2\pi\epsilon_{\mathbf{0}}\mathbf{R}}$$

iii) Electric filed inside at a distance 'r' from the axis

$$\mathbf{E} = \frac{\lambda \mathbf{r}}{2\pi \boldsymbol{\varepsilon}_0 \mathbf{R}^2}$$



b) Plane sheet of charge :

$$E = \frac{\sigma}{2\epsilon_0}$$
, where  $\sigma$  is the surface charge density.

c) Near a charge conducting surface :

$$E = \frac{\sigma}{\epsilon_0}$$

d) Charged conducting spherical shell :

$$\vec{E}_{in} = 0, r < R$$

$$\vec{E}_{out} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2}, r > R$$

$$\vec{E}_{sur} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2}, r = R$$



e) Non conducting charged solid sphere :

$$\mathbf{E_{in}} = \frac{1}{4\pi\epsilon_0} \frac{\mathbf{qr}}{\mathbf{R^3}}, \mathbf{r} < \mathbf{R}$$



$$\vec{E}_{out} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2}, r > R$$
$$\vec{E}_{sur} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2}, r = R$$

f) Charged ring : ¶ E Special cases :- $E_{axial} = \frac{1}{4\pi\epsilon_0} \frac{qx}{(R^2 + x^2)^{3/2}}$ i) If x < R and  $x^2 << R^2$ ,  $E = \frac{1}{4\pi\epsilon_0} \frac{qx}{R^3},$ Ο  $\frac{R}{\sqrt{2}}$ ii) If x > R and  $x^2 >> R^2$ ,  $E = \frac{1}{4\pi\epsilon_0} \frac{q}{x^2}$ Note :  $E_{max}$  at  $r = R / \sqrt{2}$ . g) Dipole : In terms of polar coordinates,

$$E_{\mathbf{r}} = \frac{1}{4\pi\epsilon_{0}} \frac{2P\cos\theta}{r^{3}}$$

$$E_{\theta} = \frac{1}{4\pi\epsilon_{0}} \frac{P\sin\theta}{r^{3}}$$

$$E_{\mathbf{R}} = \sqrt{E_{\mathbf{r}}^{2} + E_{\theta}^{2}}$$

$$E_{\mathbf{R}} = \frac{P}{4\pi\epsilon_{0}r^{3}} \sqrt{1 + 3\cos^{2}\theta}$$
Its direction,  $\phi = \tan^{-1}\left(\frac{\tan\theta}{2}\right)$ 



 $\vec{P}$ 

Torque on a dipole :

 $\vec{\boldsymbol{\tau}} = \vec{P} \times \vec{E}$ 

Potential energy of Dipole :

 $U = - \stackrel{\rightarrow}{P} \stackrel{\rightarrow}{.} \stackrel{\rightarrow}{E}$ 

Electric Potential due to various charge distribution :

a) Charged ring :

i) At the centre:- 
$$V = \frac{1}{4\pi\epsilon_0} \frac{q}{R}$$
 ( $O$ ) x P ring

ii) On the axis at a distance x from the centre:-  $V = \frac{1}{4\pi\epsilon_0} \frac{q}{\sqrt{R^2 + x^2}}$ 

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i) At a distance x from the centre,

$$V = \frac{\sigma}{2\epsilon_0} \left[ \sqrt{R^2 + x^2} - x \right]$$

ii) At the centre,

$$V = \frac{\sigma R}{2\epsilon_0}$$

iii) At a large distance x (>> R),

$$V = \frac{1}{4\pi\epsilon_0} \frac{q}{x}$$

Here, the disc behaves as a point charge.

iv) At the edge of the disc,

$$V = \frac{\boldsymbol{\sigma}R}{\boldsymbol{\epsilon_0}}$$

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Spherical shell :  $V_{in} = \frac{1}{4\pi\epsilon_0} \frac{q}{R}$   $V_{out} = \frac{1}{4\pi\epsilon_0} \frac{q}{r}$ Nonconducting sphere :

$$V_{in} = \frac{1}{4\pi\epsilon_0} \frac{q}{R} \left[ \frac{3}{2} - \frac{r^2}{2R^2} \right]$$
$$V_{sur} = \frac{1}{4\pi\epsilon_0} \frac{q}{R}; V_{out} = \frac{1}{4\pi\epsilon_0} \frac{q}{r}$$

- 6. Capacitance of a parallel plate capacitor,  $C = \frac{\epsilon_0 A}{d}$
- 7. Voltage across capacitor,  $V = \frac{Q}{C}$
- 8. Elements in series :  $\frac{1}{1} = \frac{1}{1} + \frac{1}{1}$ , R = R<sub>1</sub> + R<sub>2</sub>

$$C C_1 C_2$$
  
Elements in parallel :

$$C = C_1 + C_2$$
;  $\frac{1}{R} = \frac{1}{R_1} + \frac{1}{R_2}$ 

**10.** If a dielectric is placed inside the capacitor,  $E = \frac{E_0}{V_0}$ ,  $V = \frac{V_0}{V_0}$ 

$$=\frac{1}{K}, V = \frac{1}{K}$$

**11.** Induced charged in the dielectric,

$$q_i = q \left( 1 - \frac{1}{K} \right)$$

d)

9.

**12.** Capacitance of a capacitor partially filled with dielectric of thickness t,

$$C = \frac{\boldsymbol{\epsilon_0} A}{\left(d - t + \frac{t}{K}\right)}$$



**13.** Force between the plates of a capacitor  $F = \frac{Q^2}{Q^2}$ 

$$r = \frac{c}{2\epsilon_0 A}$$

14. Capacitance of a spherical capacitor,  $C = \frac{4\pi\epsilon_0 a b}{(b-a)}$ 



**15.** Capacitance of a parallel plate capacitor,

$$C = \frac{\boldsymbol{\epsilon_0}A}{d}$$

**16.** Capacitance of a cylindrical capacitor,

C (per unit length) =  $\frac{2\pi\epsilon_0}{\ln\left(\frac{b}{a}\right)}$ 



## Numbers :

Electronic charge,  $e = 1.6 \times 10^{-19}$ 

$$\frac{1}{4\pi\epsilon_0} = 9 \times 10^9 \text{ Nm}^2 / \text{ C}^2$$
$$\epsilon_0 = 8.85 \times 10^{-12} \text{ C}^2 / \text{ Nm}^2$$

## Units :

Quantity	Units	Conversion
Electric field	N/C, V/m	1  N/C = 1 V/m
Charge	C	$1e = 1.6 \times 10^{-19} C$
Voltage	V, J/C	1V = 1 J/C

# CURRENT ELECTRICITY

# Facts:

- **1.** Sum of currents into a node is zero.
- **2.** Sum of voltage around closed loop is zero.
- **3.** The temperature coefficient of resistivity is negative for semiconductor.

Q = charge	$v_d$ = drift velocity
i, I = current	j = current density
$\rho$ = resistivity	R = resistance
t = thickness	K = dielectric constant

# Formulae :

**1.** Electric current,

 $I = n \neq A v_d$ 

**2.** Resistance of a wire,

$$\mathsf{R} = \rho \frac{\mathsf{L}}{\mathsf{A}}$$

**3.** Current density,

$$J = \frac{I}{A} = n q v_d$$

- **4.** Voltage across the resistor, V = IR
- 5. Ohm's law,  $E = \rho J$
- **6.** Power dissipated in resistor :

$$P = I^2 R = \frac{V^2}{R}$$

7. Charge on a capacitor in an RC – circuit,  $Q(t) = Q_0 (I - e^{-t/RC})$  where  $Q_0$  is the charge at t = 0

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8. Current through a resistor in an RC – circuit,  $I(t) = I_0 e^{-t/\tau}$ , where  $\tau = RC$ 

$$+E$$
  $-IR$   $-Q/C$ 

**9.** Grouping of cells :

a) Series combination :-  

$$I = \frac{n\epsilon}{(nr+R)}$$

$$I = \frac{n\epsilon}{n cells}$$

$$R$$

If the polarity of 'm' cells is reversed.

$$\mathbf{I} = \frac{(n-2m)\boldsymbol{\varepsilon}}{(\mathbf{R}+n\mathbf{r})}$$

b) Parallel combination :-





c) Mixed combination :-



#### Ammeter :

$$\mathbf{S} = \left(\frac{\mathbf{I}_{\mathbf{g}}}{\mathbf{I} - \mathbf{I}_{\mathbf{g}}}\right) \mathbf{G}$$

Percentage error in measuring current through an ammeter,

%Error =  $\left(\frac{R'}{R+R'}\right) \times 100$  where  $R' = \frac{GS}{G+S}$ 





#### **Potentiometer :**

Comparing the emf of the cells,  $\frac{\epsilon_1}{\epsilon_2} = \frac{\ell_1}{\ell_2}$ 

Internal resistance of a battery,  $\mathbf{r} = \mathbf{R} \left( \frac{\boldsymbol{\ell}}{\boldsymbol{\ell}'} - 1 \right)$ 

### Wheatstone Bridge :

$$\frac{R_1}{R_1} = \frac{R_3}{R_3}$$

R<sub>2</sub> R<sub>4</sub>

Under the above condition there will be no current through Galvanometer.



#### Units :

Quantity	Units	Conversion
Capacitance	F	I F = IC/V
Current	A	IA = IC/S
Resistance	Ω	$I\mathbf{\Omega} = IV / A$

## THERMAL EFFECTS OF CURRENTS

# Joules law of heating :

Heat produced in a resistor, H =  $I^2Rt$ 

#### $H = I^2 R t$

Seeback Effect :

Thermo emf,  $\mathbf{E} = \alpha t + \beta t^2$ 

# MAGNETIC EFFECTS OF CURRENTS

B = magnetic induction	$\phi$ = flux
q = charge	V = velocity
F = force	N = no. of turns
I = current	$\mu$ = magnetic dipole moment

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#### Facts :

- **1.** Force on a moving charge in magnetic filed is  $\perp^{\mathbf{r}}$  to both  $\overrightarrow{\mathbf{v}}$  and  $\overrightarrow{\mathbf{B}}$ .
- **2.** Net magnetic force acting on any closed current loop in a uniform magnetic field is zero.
- **3.** Magnetic filed of long straight wire circles around wire.
- **4.** Parallel wires carrying current in the same direction attract each other. **Formulae :**
- **1.** Force on a charged Particle,  $\vec{F} = q \left( \vec{v} \times \vec{B} \right)$  $F = qvB(\sin\theta)$
- When a particle enters into a ⊥<sup>r</sup> magnetic field, it describe a circle. Radius of the circular path,

$$r = \frac{mv}{qB} = \frac{\sqrt{2Km}}{qB}$$

- **3.** Time period,  $T = \frac{2\pi m}{qB}$
- **4.** Magnetic force on a segment of wire,

$$\vec{F} = \vec{l} \cdot \vec{\ell} \times \vec{B}$$

**5.** Force between parallel current carrying wires,

$$\frac{\mathrm{F}}{\boldsymbol{\ell}} = \frac{\boldsymbol{\mu_0}}{2\boldsymbol{\pi}} \frac{\mathrm{I_1}\mathrm{I_2}}{\mathrm{r}}$$

**6.** A current carrying loop behaves as a magnetic dipole of magnetic dipole moment,

$$\vec{\mu} = NI \vec{A}$$

- **7.** Torque on a current loop,  $\vec{\tau} = \vec{\mu} \times \vec{B}$
- **8.** Magnetic field due to a current currying wire,

$$\vec{\mathbf{B}} = \frac{\boldsymbol{\mu_0} \, \mathbf{I}}{4\pi} \int \frac{\vec{\mathbf{d}\ell \times \mathbf{r}}}{\mathbf{r^2}}$$



9. Ampere's law

 $\oint \vec{B}.\vec{d\ell} = \mu_0 \ I_{enc}$ 

# Magnetic Field due to various current distributions :

1) Current in a straight wire :-

$$\mathbf{B} = \frac{\boldsymbol{\mu_0}\mathbf{I}}{4\pi\mathbf{b}}(\sin\alpha + \sin\beta)$$

2) For an infinitely long straight wire :-  $\alpha = \beta = \pi / 2$  $B = \frac{\mu_0 I}{4\pi b}$ 



**3)** On the axis of a circular coil :-

$$B = \frac{\mu_0 NIR^2}{2(R^2 + x^2)^{3/2}}$$

4) At the centre of the circular coil :- $B = \frac{\mu_0 I}{2R}$ 



5) For a circular arc,  

$$B = \frac{\mu_0 I}{4\pi R} \theta$$

6) Along the axis of a solenoid,  $B_{c} = \frac{\mu_{0}nI}{2}(\cos\theta_{2} - \cos\theta_{1})$ where  $n = \frac{N}{\ell}$  (No. of turns per unit length)



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7) For a very long solenoid,  $B_{\mathbf{C}} = \mu_{\mathbf{0}} n \mathbf{I}$ 

8) At then end of a long solenoid,  $B = \frac{\mu_0 nI}{2}$ 

#### MAGNETOSTATICS

 Magnetic - Moment of a bar magnet : M = m × 2l where 'm' is the pole Strength.



2. Force between two poles of strength  $m_1$  and  $m_2$  separated by a distance

'r' is given by,  $F = \frac{\mu_0}{4\pi} \frac{m_1 m_2}{r^2}$  where 'r' is in metre and m in Amp-metre.

Torque on a bar magnet placed in a magnetic field,
 → → →

$$\dot{\boldsymbol{\tau}} = \mathbf{M} \times \mathbf{B}$$

and the potential energy,  $\boldsymbol{0}$ 

$$U = M.B$$

**4.** Magnetic field due to a bar magnet,

i) 
$$B_{\mathbf{p}} = \frac{\mu_{\mathbf{0}}}{4\pi} \frac{2M}{r^{\mathbf{3}}}$$

ii) 
$$B_{\mathbf{p}} = \frac{\mu_{\mathbf{0}}}{4\pi} \frac{M}{(r^{2} + \ell^{2})^{3/2}}$$
If  $r \gg \ell$ 
$$B = \frac{\mu_{\mathbf{0}}}{4\pi} \frac{M}{r^{3}}$$



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5. Earth's magnetic field,  $\frac{B_{H}}{B} = \cos \delta$ Where  $B_{H}$  is the horizontal Component of the earth's magnetic field and ' $\delta$ ' is the angle of dip.



**6.** Magnetic intensity,

$$\vec{H} = \frac{\vec{B}}{\mu_0} - \vec{I}$$
, where  $I = \frac{M}{V}$ 

- **7.**  $\vec{B} = -\mu \vec{H}$
- 8.  $I = \chi \vec{H}$ , where  $\chi$  is the magnetic susceptibility.

9. Curie's law : 
$$\chi = \frac{C}{T}$$

### **ELECTROMAGNETIC - INDUCTION AND ALTERNATING CURRENTS**

В	=	magnetic induction	¢	= flux
q	=	charge	V	= velocity
F	=	force	Ν	= no. of turns
Ι	=	current	L	= coefficient of self inductance
Μ	=	coefficient of mutual	3	= induced emf
		inductance		

1. Induced emf,  $\varepsilon = -N \frac{d\Phi}{dt} = -NA \frac{dB}{dt}$  where a is the area of a loop.

**2.** Induced current, 
$$I = \frac{\varepsilon}{R}$$

**3.** Induced electric field, 
$$\oint \vec{E} \cdot d\vec{\ell} = -\frac{d\Phi}{dt}$$

**4.** Self-inductance,

$$N\Phi = LI; \quad \epsilon = -L\frac{dI}{dt}$$

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11. L-C-Oscillations :  

$$\frac{d^{2}q}{dt^{2}} = -\left(\frac{1}{LC}\right)q$$

$$q = q_{0} \cos \omega t \text{ where, } \omega = \frac{1}{\sqrt{LC}}$$
12. R.M.S. current,  $I_{rms} = \frac{I_{0}}{\sqrt{2}}$ 
13. In RC - circuit  
Peak current,  

$$I_{0} = \frac{\varepsilon_{0}}{z} = \frac{\varepsilon_{0}}{\sqrt{R^{2} + (1/\omega C)^{2}}} 14.$$

$$\sum_{k=1}^{L} \sum_{0}^{k} \sum_{k=1}^{k} \sum_{k=1}^{k}$$

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16. In LCR - Circuit :  

$$I = \frac{\varepsilon_{0}}{\sqrt{R^{2} + (\frac{1}{\omega C} - \omega L)^{2}}} \sin(\omega t - \phi)$$

$$\varepsilon = \varepsilon_{0} \sin \omega t$$

$$\frac{1}{\omega C} - \omega L$$

i) If 
$$\frac{1}{\omega C} > \omega L$$
, current leads the voltage.

ii) If 
$$\frac{1}{\omega C} < \omega L$$
, current legs behind the voltage.

iii) If 
$$\frac{1}{\omega C} = \omega L$$
, current is in phase with the voltage.

$$I = \frac{\epsilon_0}{\sqrt{R^2 + \left(\frac{1}{\omega C} - \omega L\right)^2}}$$

If the angular frequency  ${}^{\prime}\omega{}^{\prime}$  varies then  $I_0$  also varies.

I<sub>0</sub> is maximum, when 
$$\frac{1}{\omega C} - \omega L = 0$$
  
or  $\omega = \frac{1}{\sqrt{LC}}$   
 $f = \frac{1}{2\pi\sqrt{LC}}$ 

This is called the resonance frequency of the circuit.

**17.** Power in an A. C. circuit,

 $P = V_{rms} I_{rms} \cos \phi$  where  $\cos \phi$  is the power factor.

- i) For a purely resistive circuit,  $\phi = 0$
- ii) For a purely reactive circuit,  $\phi = \pi/2$ , or  $-\pi/2$  $\therefore \cos \phi = 0$
- **18.** Transformer :

$$\frac{\boldsymbol{\epsilon_1}}{\boldsymbol{\epsilon_2}} = \frac{N_1}{N_2}$$
 where N1 and N<sub>2</sub> are the number of turns in the

. .

primary and secondary coils respectively.

conductor

# **Electromagnetic – Induction**

Induced electric filed, 
$$\oint \vec{E} \cdot d\vec{\ell} = -\frac{d\Phi}{dt}$$
  
Motional emf =  $\epsilon = \int_{a}^{b} (\vec{v} \times \vec{B}) \cdot d\vec{\ell}$ 

#### Modified Faraday's law

$$\boldsymbol{\varepsilon} = \oint \underbrace{(\overrightarrow{v} \times \overrightarrow{B}).d \ \overrightarrow{\ell}}_{\substack{\text{Motion of a} \\ \text{conductor in a} \\ \text{magnetic field}}} = - \underbrace{\overrightarrow{A}. \frac{d \overrightarrow{B}}{dt}}_{\substack{\text{Variation of} \\ \text{magnetic field} \\ \text{in a} \\ \text{stationary}}}$$

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# RAY OPTICS

u = distance of the object from the lens/mirror	
v = distance of the image from the lens/mirror	
m = magnification	i = angle of incident
r = angle of refraction/reflection	n = refractive index
$\theta_{c}$ = critical angle	$\delta$ = angle of
•	deviation
R = radius of curvature	P = power

**1.** Spherical mirrors,

$$\frac{1}{v} + \frac{1}{u} = \frac{1}{f}, \qquad m = -\frac{v}{u}$$
2. Refraction at plane surfaces,  

$$n = \frac{\sin i}{\sin r} = \frac{\text{realdepth}}{\text{apparent depth}}$$
critical angle,  $\theta_{c} = \sin^{-1}\left(\frac{1}{n}\right)$ 
3. Refraction at spherical surface,  

$$\frac{n_{2}}{v} - \frac{n_{1}}{u} = \frac{n_{2} - n_{1}}{R}, m = \frac{n_{1}v}{n_{2}u}$$
4. Refraction through thin lenses,  

$$\frac{1}{f} = (n-1)\left(\frac{1}{R_{1}} - \frac{1}{R_{2}}\right)$$

$$\frac{1}{f} = \frac{1}{v} - \frac{1}{u}, m = \frac{v}{u}$$

$$P = \frac{1}{f}, \text{ (f should be in metre)}$$
5. Prism,  

$$r + r' = A,$$

$$\delta = i + i' - A$$

$$\sin \frac{A + \delta_{m}}{k}$$

 $n = \frac{\sin \frac{A + \delta_{m}}{2}}{\sin \frac{A}{2}}$ 

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Refraction at plane surfaces, Normal shift =  $\left(1 - \frac{1}{n}\right)t$ , t is the thickness of 6. the glass slab. For small 'A' and 'I',  $\boldsymbol{\delta} = (n-1)A$ 7. Combination of lens  $\frac{1}{F} = \frac{1}{f_1} + \frac{1}{f_2} + \dots$ 8. When lens are 'd' distance apart  $\frac{1}{F} = \frac{1}{f_1} + \frac{1}{f_2} - \frac{d}{f_1 f_2}$ 9. **WAVE OPTICS** c = speed of light, a = amplitude  $\eta$  = refractive index of the material, I = intensityv = speed of light in the material, W = fringe width $\Delta x = path difference$  $\lambda$  = wavelength  $\delta$  = phase difference d = distance between the slits D = distance between the slit and the t = thickness of glass slab screen  $v = \frac{c}{n}$  where 1. c = speed of light,  $\eta$  = refractive index of the material and v = speed of light in that material Young's double slit experiment, 2.  $a = \sqrt{a_1^2 + a_2^2 + 2a_1a_2\cos\delta} \ , \quad I = I_1 + I_2 + 2\sqrt{I_1\,I_2}\cos\delta$ for bright fringes,  $\Delta x = n\lambda$ for dark fringes,  $\Delta \mathbf{x} = \left(n - \frac{1}{2}\right) \boldsymbol{\lambda}$  n = 1, 2, 3 ...Fringes width =  $\frac{D\lambda}{d}$  $v = \frac{c}{\mu}, c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}, v = \frac{1}{\sqrt{\mu\epsilon}}$ 3.

Young's double slit experiment, 4.  $a=\sqrt{a_1^2+a_2^2+2a_1a_2\cos\delta}$  ,  $I=I_1+I_2+2\sqrt{I_1\,I_2}\cos\delta$ for bright fringes,  $\Delta x = n\lambda$ for dark fringes,  $\Delta x = \left(n - \frac{1}{2}\right)\lambda$  n = 1, 2, 3, ...W =  $\frac{D\lambda}{d}$ Shifting of fringes : Shift =  $\frac{(\mu - 1)tD}{d}$ 5. 6. Optical path length =  $\mu t$ Number of fringes shifted  $=\frac{\text{shift}}{\text{firing width}}=\frac{(\mu-1)t}{d}$ 7. Dispersive Power,  $\boldsymbol{\omega} = \frac{\boldsymbol{\mu}_{\mathbf{v}} - \boldsymbol{\mu}_{\mathbf{r}}}{\boldsymbol{\mu}_{\mathbf{y}} - 1}$ 8. Dispersive without average deviation :  $\frac{A}{A'} = \frac{\mu'_y - 1}{\mu_w - 1}$ 9. Average deviation without dispersion :  $\frac{A}{A'} = \frac{\mu'_{\nu} - \mu'_{r}}{\mu'_{\nu} - \mu'_{r}}$ 10. Net average deviation  $\delta_{\mathbf{r}} = (\boldsymbol{\mu}_{\mathbf{y}} - 1)A\left(1 - \frac{\boldsymbol{\omega}}{\boldsymbol{\omega}_{\mathbf{r}}}\right)$ 11. **ELECTROMAGNETIC WAVES** 1

1. Speed of electromagnetic waves, 
$$v = \frac{1}{\mu\epsilon}$$

**2.** Electromagnetic waves and transverse, E = CB

PHYSICS

Wave-Band	Origin	Sources
X-radiation	<ul><li>i) High energy changes in electron structures of atoms</li><li>ii) Decelerated electrons</li></ul>	X-ray tubes
Gamma radiation	Energy changes in nuclei of atoms	Radioactive substance
Ultraviolet radiation	Fairly high energy changes in electron structure of atoms	<ul> <li>i) Very hot bodies, e.g.</li> <li>the electric arc.</li> <li>ii) Electric discharge</li> <li>through gases,</li> <li>particularly, mercury</li> <li>vapour in quartz</li> <li>envelopes</li> </ul>
Visible Radiation	Energy changes in electron structure of atoms	Various lamps, flames and anything at or above red-heat
Infrared Radiation	Low energy changes in electron structure of atoms	All Matter over a wide range of temperature from absolute zero upwards
Radio wave	<ul><li>i) High frequency oscillatory electric currents</li><li>ii) Very low energy changes in electron structure of atoms.</li></ul>	Radio transmitting circuits.



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#### **ELECTRONS AND PHOTONS**

Ρ	= momentum	h = Plank's constant
λ	= wavelength	c = speed of light
F	= frequency	$\phi$ = work function

- 1. Momentum of a photon,  $P = \frac{h}{\lambda}$
- **2.** Energy of a photon,  $E = hf = \frac{hc}{\lambda}$
- **3.** Photoelectric equation,  $KE_{max} = \frac{hC}{\lambda} \phi$  $KE_{max} = h(f - f_0)$
- 4. To take place photoelectric effect,  $\lambda \leq \lambda_0$
- 5. For a one electron atom,  $E_n = -13.6 \frac{z^2}{n^2} eV$

$$r_n = 5.29 \times 10^{-11} \frac{n^2}{z}$$
 meters

6. If an electron jumps from m<sup>th</sup> orbit to n<sup>th</sup> orbit,

$$\frac{1}{\lambda} = Rz^{2} \left[ \frac{1}{n^{2}} - \frac{1}{m^{2}} \right], \text{ where } m > n$$

- 7. Mosley's law,  $\sqrt{f} = a(z b)$  where a b are constants.
- 8. The minimum wavelength of x-rays,  $\lambda_{\min} = \frac{hc}{eV}$

## ATOMS, MOLECULES AND NUCEI

n = no. of nuclei	$t_{1/2}$ = half life
Z = atomic no.	

- **1.** Nuclear radius,  $R = R_0 A^{1/3}$ ,  $R_0 = 1.1 \times 10^{-15}$  metre
- **2.** Mass energy equivalence,  $\Delta E = \Delta m C^2$
- **3.** Radioactive decay,  $N(t) = N_0 e^{-\lambda t}$  where  $\lambda$  is the decay constant.
- 4. Radioactive Half Life,  $t^{1/2} = \frac{0.693}{2}$

# SOLIDS AND SEMICONDUCTOR DEVICES

1.	Intrinsic semiconductors,	$n_i = n_e = n_h$
2.	Doped semiconductors,	$n_{i}^{2} = n_{e}n_{h}$
3.	Conductivity,	$\boldsymbol{\sigma} = e(\mathbf{n_e}\boldsymbol{\mu_h} + \mathbf{n_h}\boldsymbol{\mu_h})$
4.	Current gains,	$\alpha = \frac{\beta}{1+\beta}, \ \beta = \frac{\alpha}{1-\alpha}$
5.	Alternating current power gain	= $\frac{\text{output power}}{\text{input power}}$

# IMPORTANT FACTS AND FORMULAE FOR JEE IIT - CHEMISTRY

#### SOME BASIC CONCEPTS

- **1 mole** = N<sub>Avg</sub> × number of species = 6.023×10<sup>23</sup> species i.e., atoms, molecules, ions, etc.
- 2. Atomic mass = Mass of one atom Gram-atomic mass = Mass of one mole of atoms

= Mass of  $6.023 \times 10^{23}$  atoms in gms.

e.g. Atomic mass of O is 16 amu. gm-atomic mass of O is 16 gm.

: 16 gm O-contains  $6.023 \times 10^{23}$  oxygen atoms.

Atomic mass =  $\frac{\text{Average mass of an atom}}{1/12 \times \text{Mass of an atom of C}^{12}}$ 

Average atomic mass =  $\frac{\text{R.A.(1)} \times \text{M.No} + \text{R.A.(2)} \times \text{M.No}}{\text{R.A.(1)} + \text{R.A.(2)}}$ 

Here R.A = Relative Abundance, Mass No. = Mass number.

3. 1 amu (atomic mass unit) =  $\frac{1}{N_{Avg}}$  = 1 Avogram

 $=\frac{1}{6.023 \times 10^{23}}$  gm = 1.66 × 10<sup>-24</sup> gm = 1 Dalton

#### 4. **Molecular weight** = Weight of one molecule

Molar mass or gm-molecular weight = weight of one mole of molecule

= wt. of  $6.023 \times 10^{23}$  molecules

5. **Moles** =  $\frac{\text{Weight(gm)}}{\text{Molar mass (gm / mole)}} = \frac{\text{volume of gas at STP(L)}}{22.4 \text{ lit.}}$ 

= Molarity × Volume (in L)